



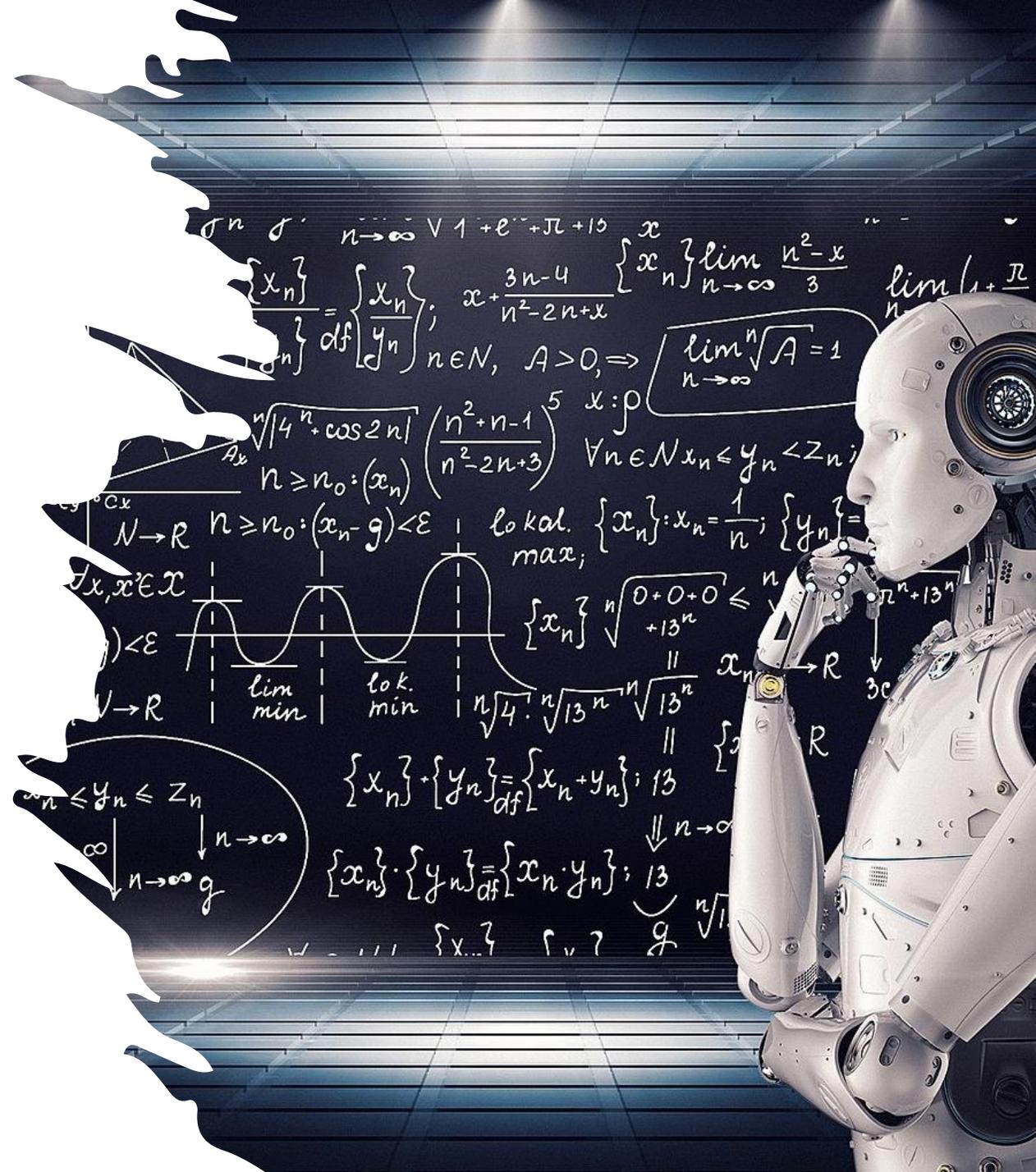
UNIVERSITY
OF WARSAW

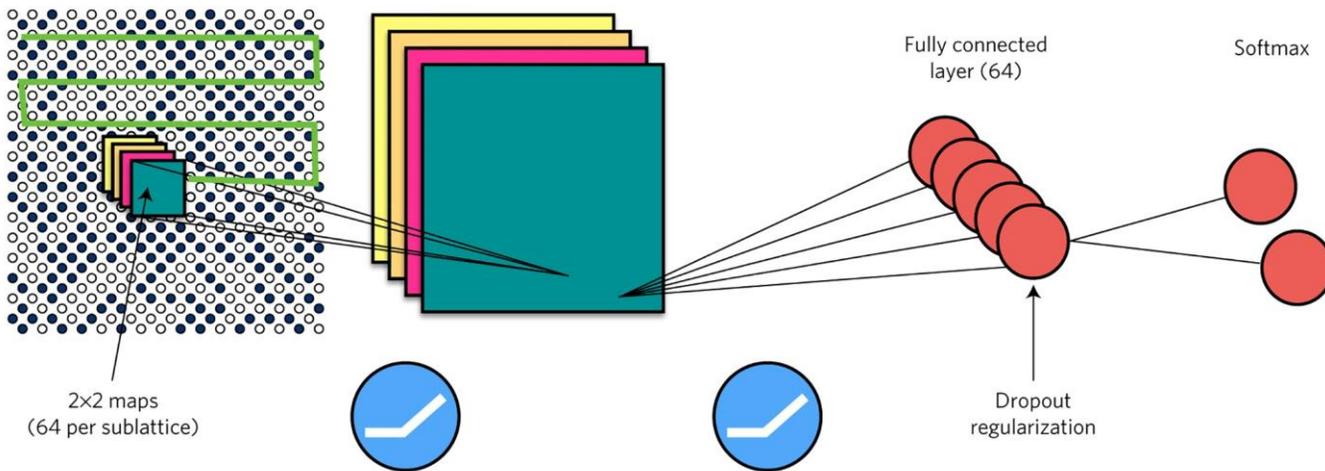
ICFO^R

Towards interpretable and reliable machines learning physics

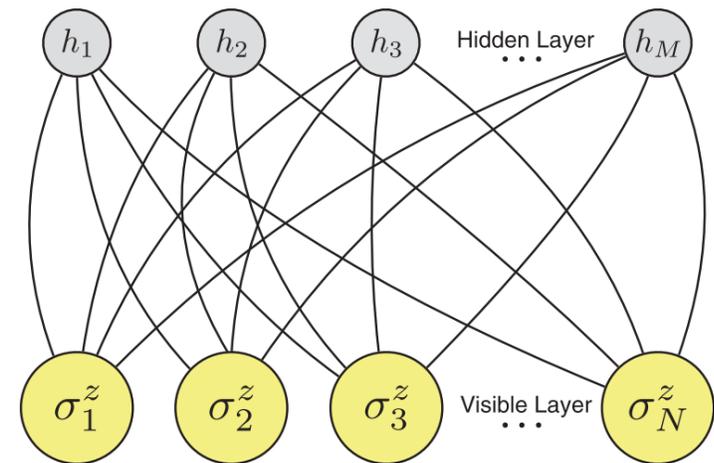
Anna Dawid

Mach. Learn.: Sci. Technol. 3, 015002 (2022)

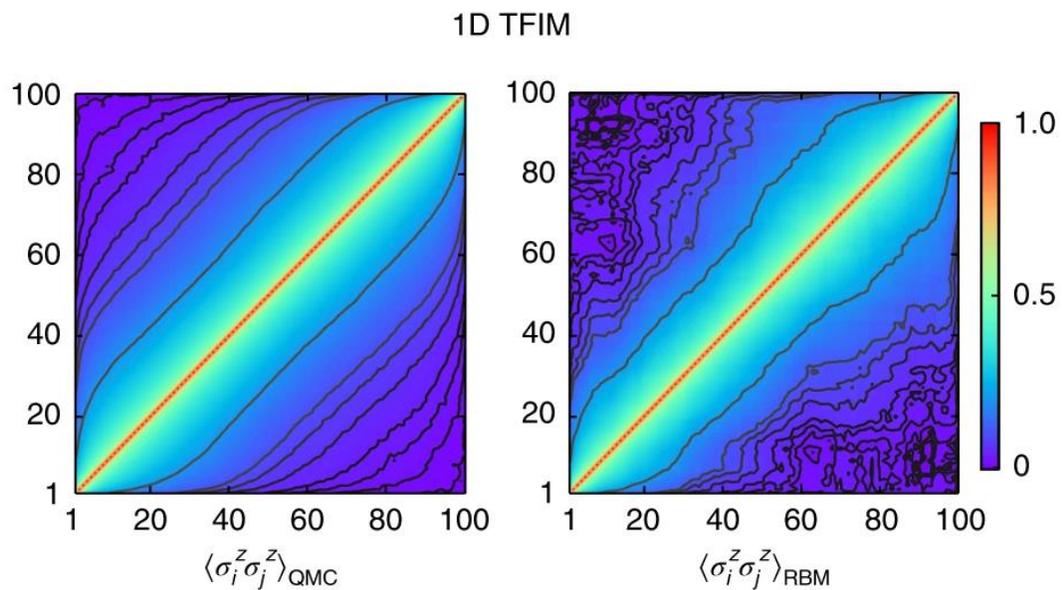




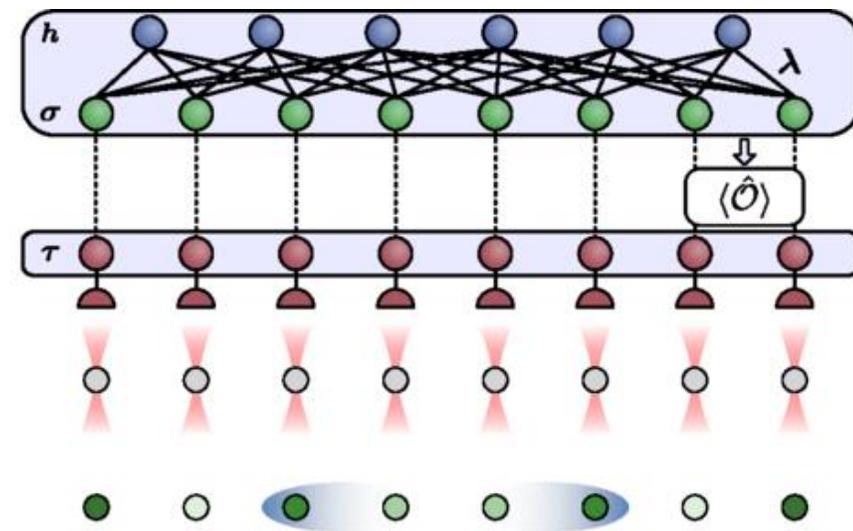
Carrasquilla & Melko, Nat. Phys. **13**, 431-434 (2017)



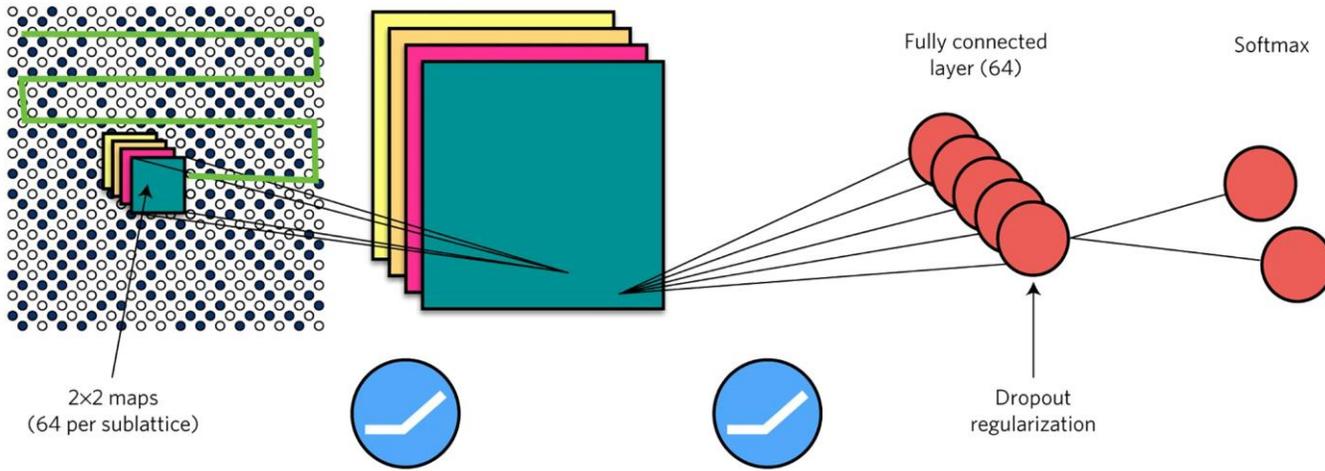
Carleo & Troyer, Science **355**, 602-606, (2017)



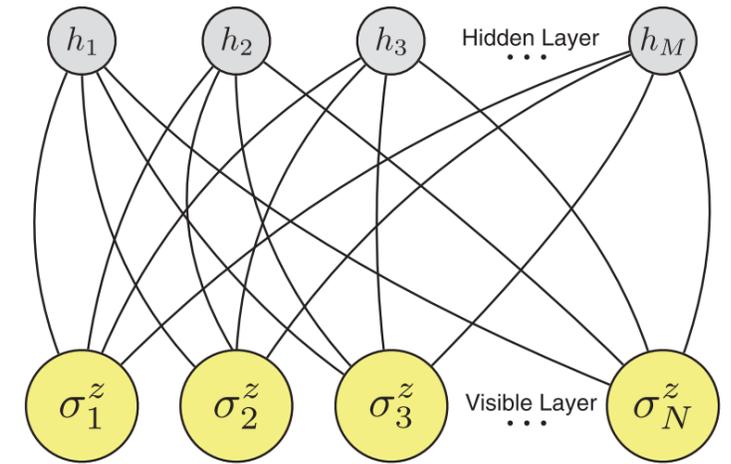
Torlai et al., Nat. Phys. **14**, 447-450 (2018)



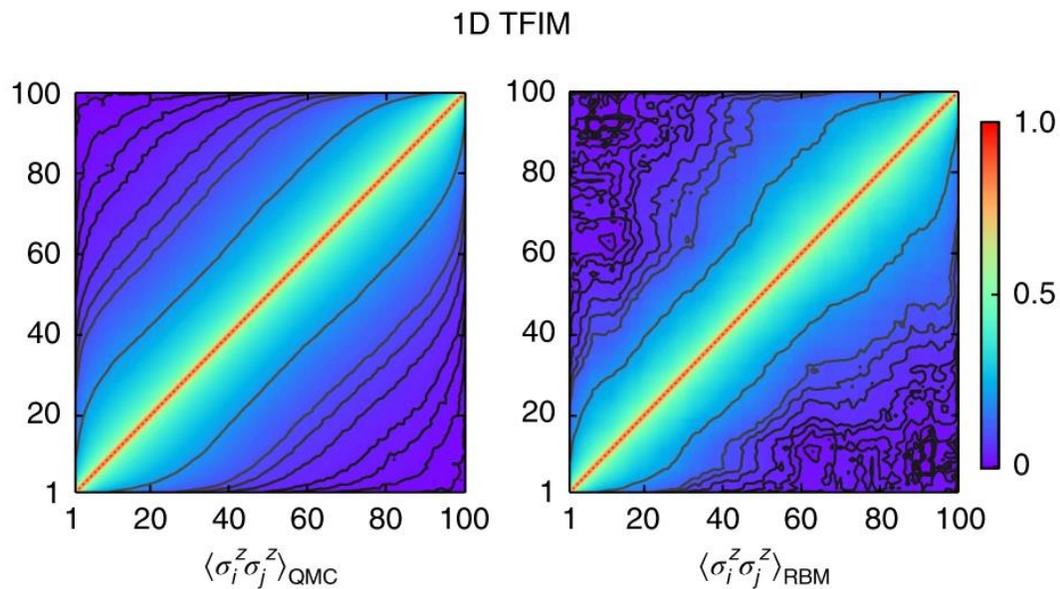
Torlai et. al., Phys. Rev. Lett. **123**, 230504 (2019)



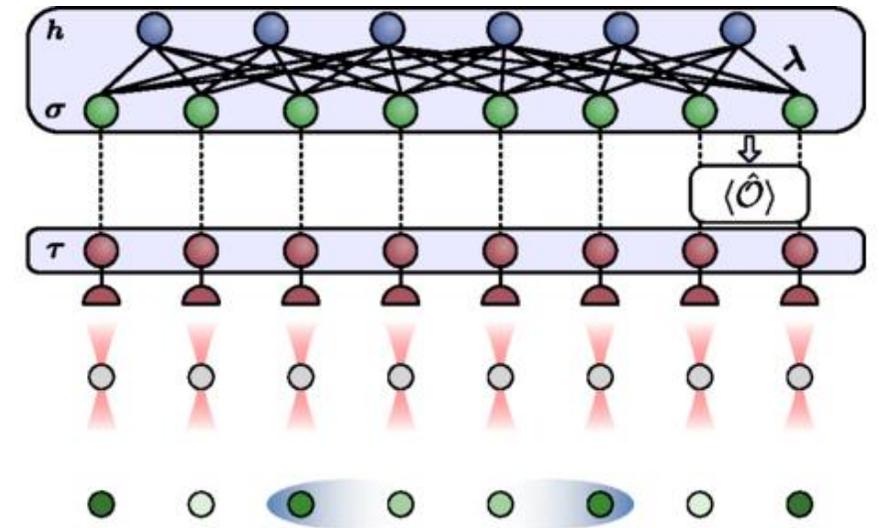
Carrasquilla & Melko, Nat. Phys. **13**, 431-434 (2017)



Carleo & Troyer, Science **355**, 602-606, (2017)

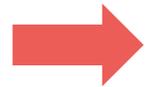


Torlai et al., Nat. Phys. **14**, 447–450 (2018)



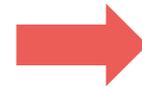
Torlai et. al., Phys. Rev. Lett. **123**, 230504 (2019)

Machines in phase classification – open problems



quantum many-body localization

- disagreement of predicted critical exponents
- high sensitivity to hyperparameters describing the training process



topological phases of matter

- learning schemes trained on raw Monte Carlo configurations were found to be not effective
- pre-engineered features are often needed



mainly recovery of **known** results, but much cheaper



general problems with ML like...

THIS IS YOUR MACHINE LEARNING SYSTEM?

YUP! YOU POUR THE DATA INTO THIS BIG PILE OF LINEAR ALGEBRA, THEN COLLECT THE ANSWERS ON THE OTHER SIDE.

WHAT IF THE ANSWERS ARE WRONG?

JUST STIR THE PILE UNTIL THEY START LOOKING RIGHT.



People worry that the computers will get too smart and take over the world, but the real problem is that they're too stupid and they've already taken over the world.

Pedro Domingos "The Master Algorithm"

- ! even small invisible changes or a different background context can completely derail predictions
- high error rates for faces from minority groups !
- ! the algorithm's hiring and insurance decisions are biased towards selecting men and white people

Some definitions

Interpretability

understanding what an ML model learns and how it makes its predictions

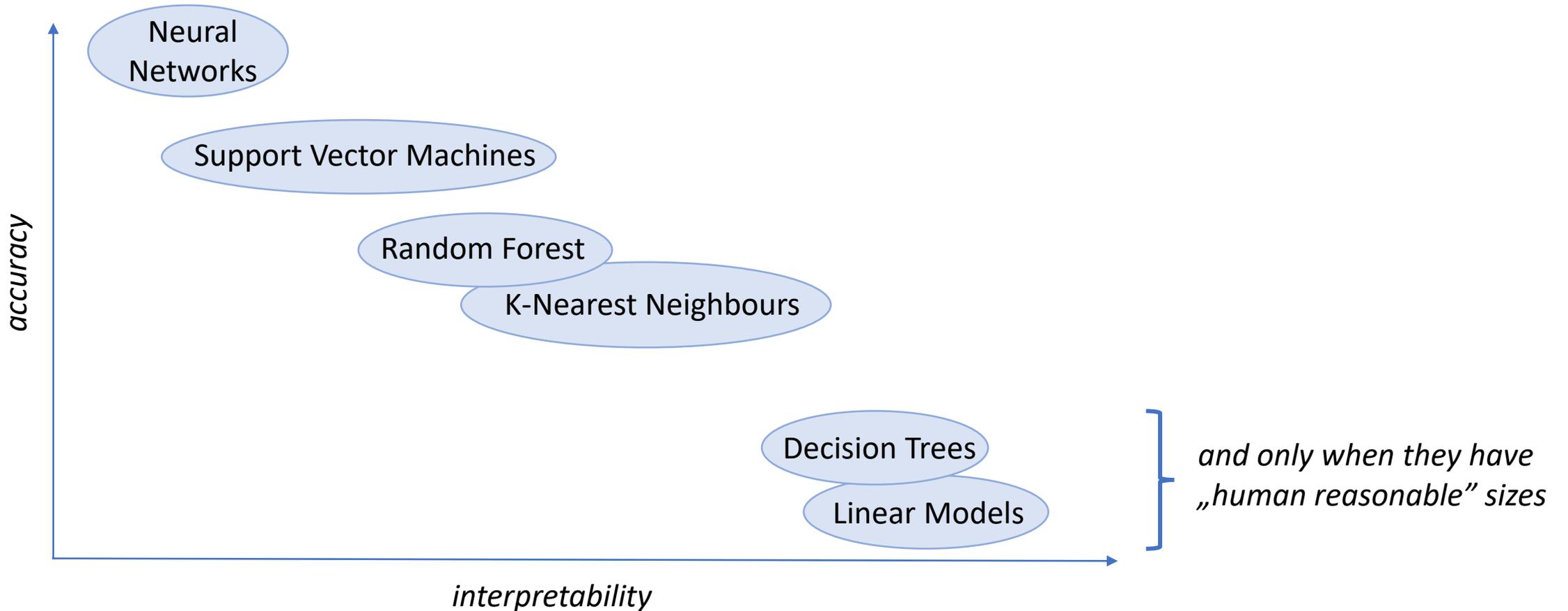
Reliability

trusting our ML model predictions (uncertainty)

These two properties are closely intertwined.



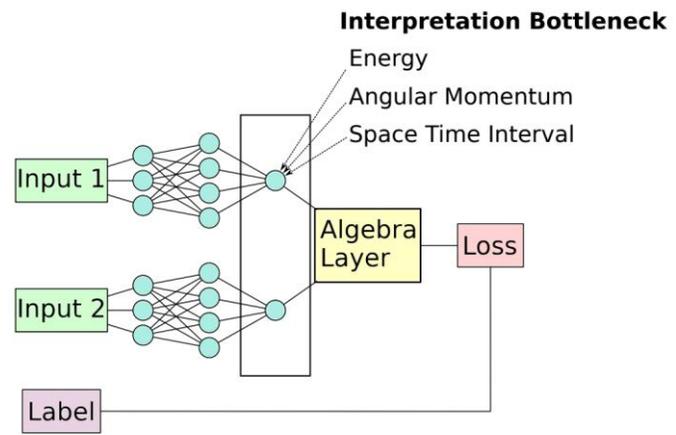
Trade-off between complexity and interpretability



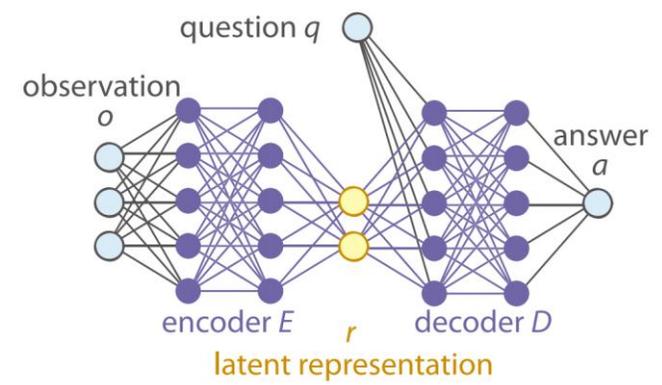


Interpretation of ML in physics so far

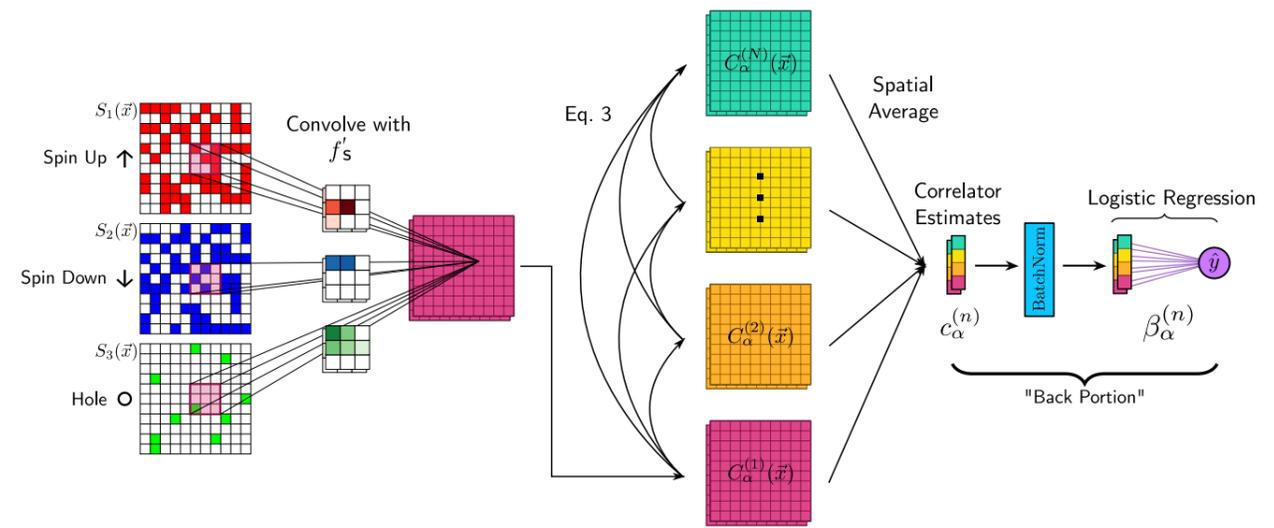
- Decision trees, kernel methods
- Bottleneck analysis



Phys. Rev. Research 2, 033499 (2020)



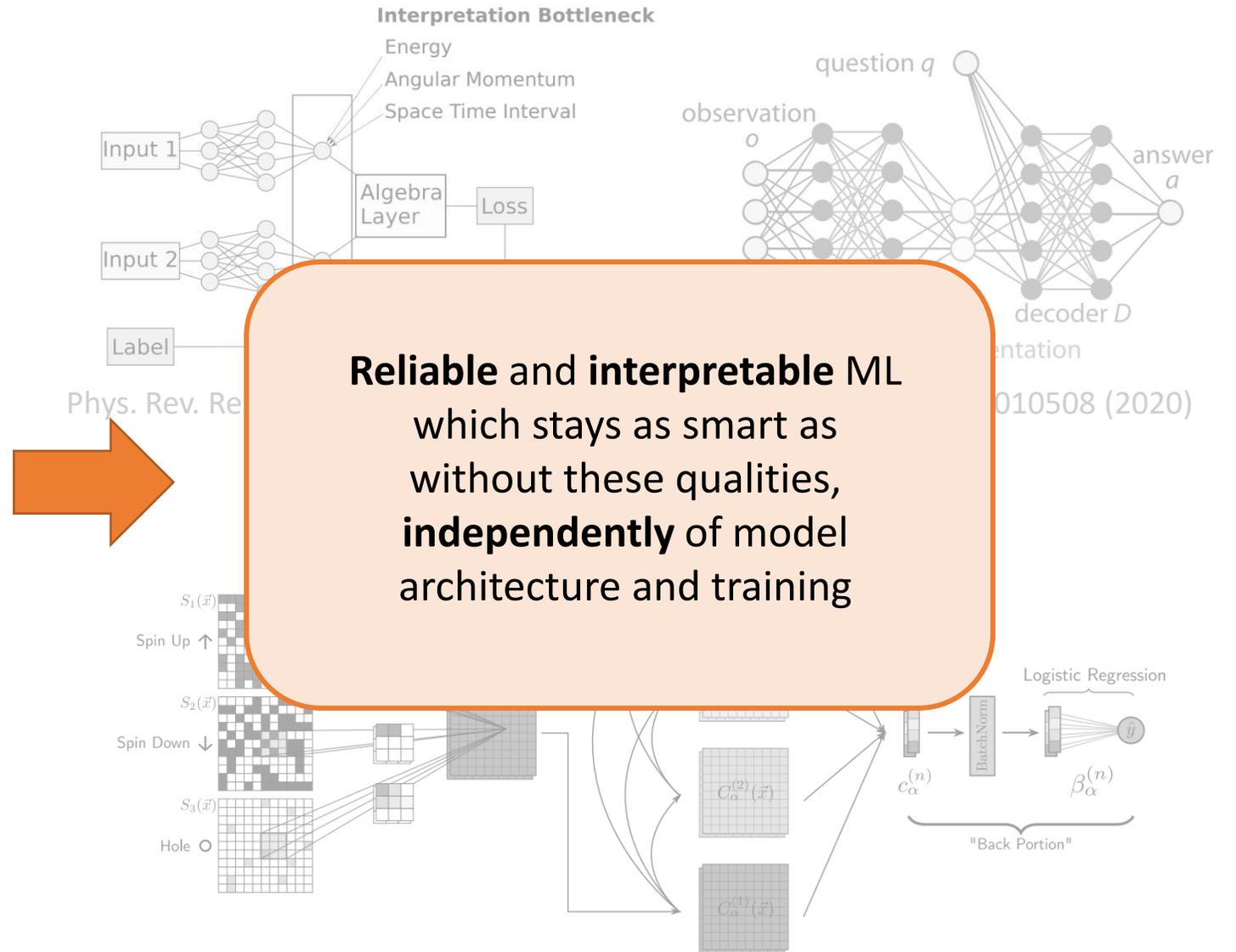
Phys. Rev. Lett. 124, 010508 (2020)



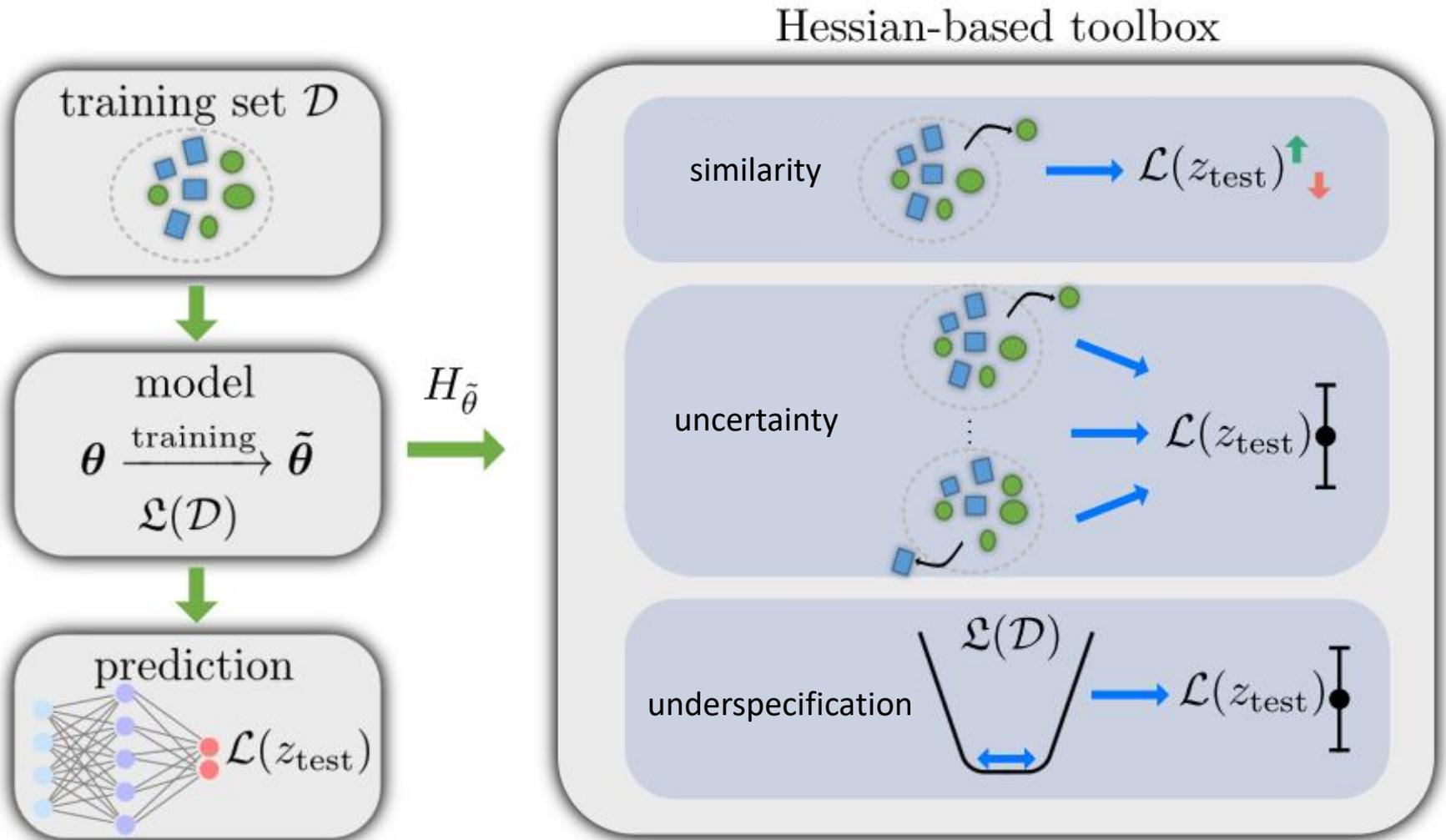
Nat. Commun. 12, 3905 (2021)

Interpretation of ML in physics so far

- Decision trees, kernel methods
- Bottleneck analysis



Hessian-based toolbox



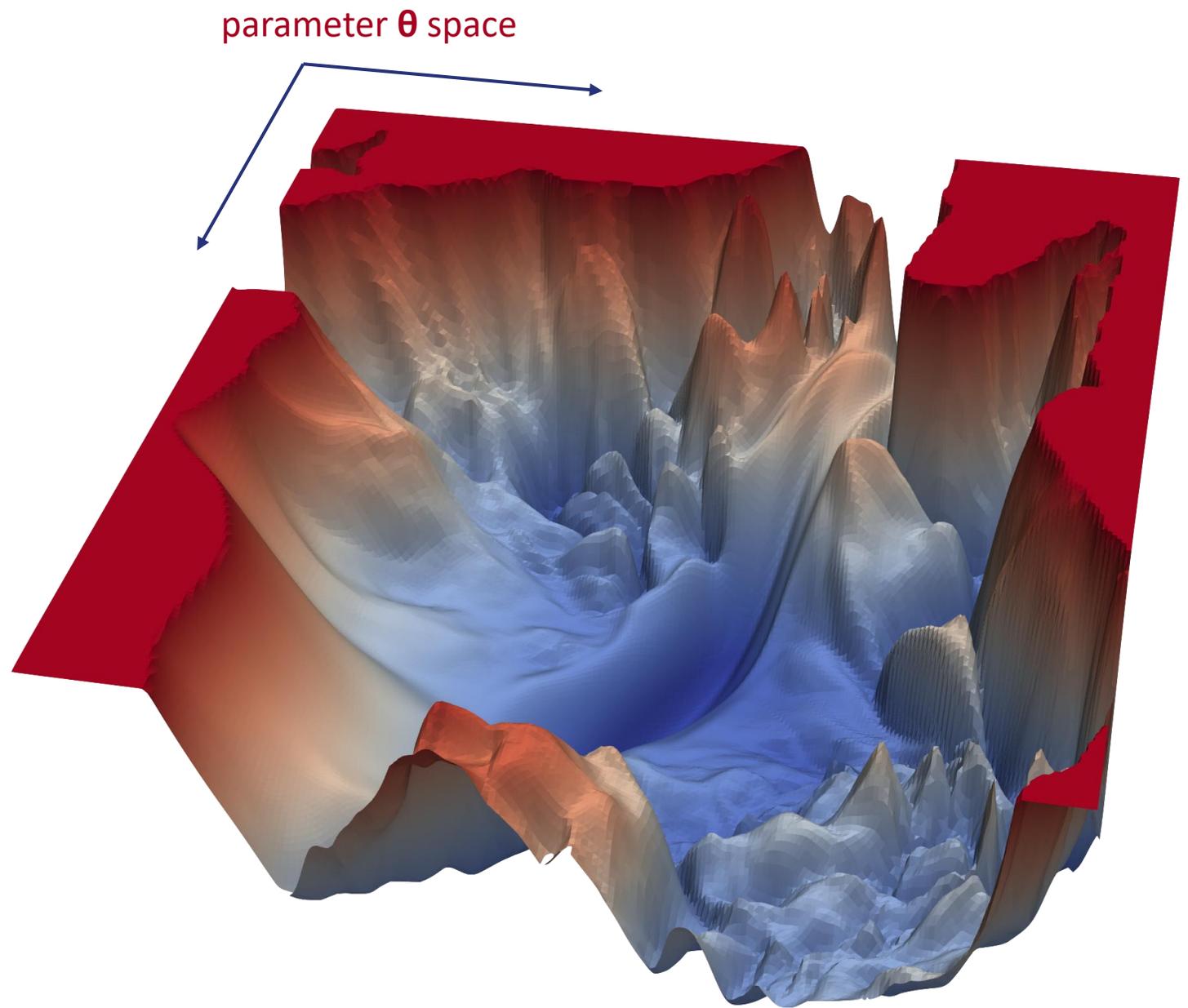
„Minimum” of ML loss landscape

(# of classes – 1): $\lambda_i > 0$

majority: $\lambda_i \approx 0$

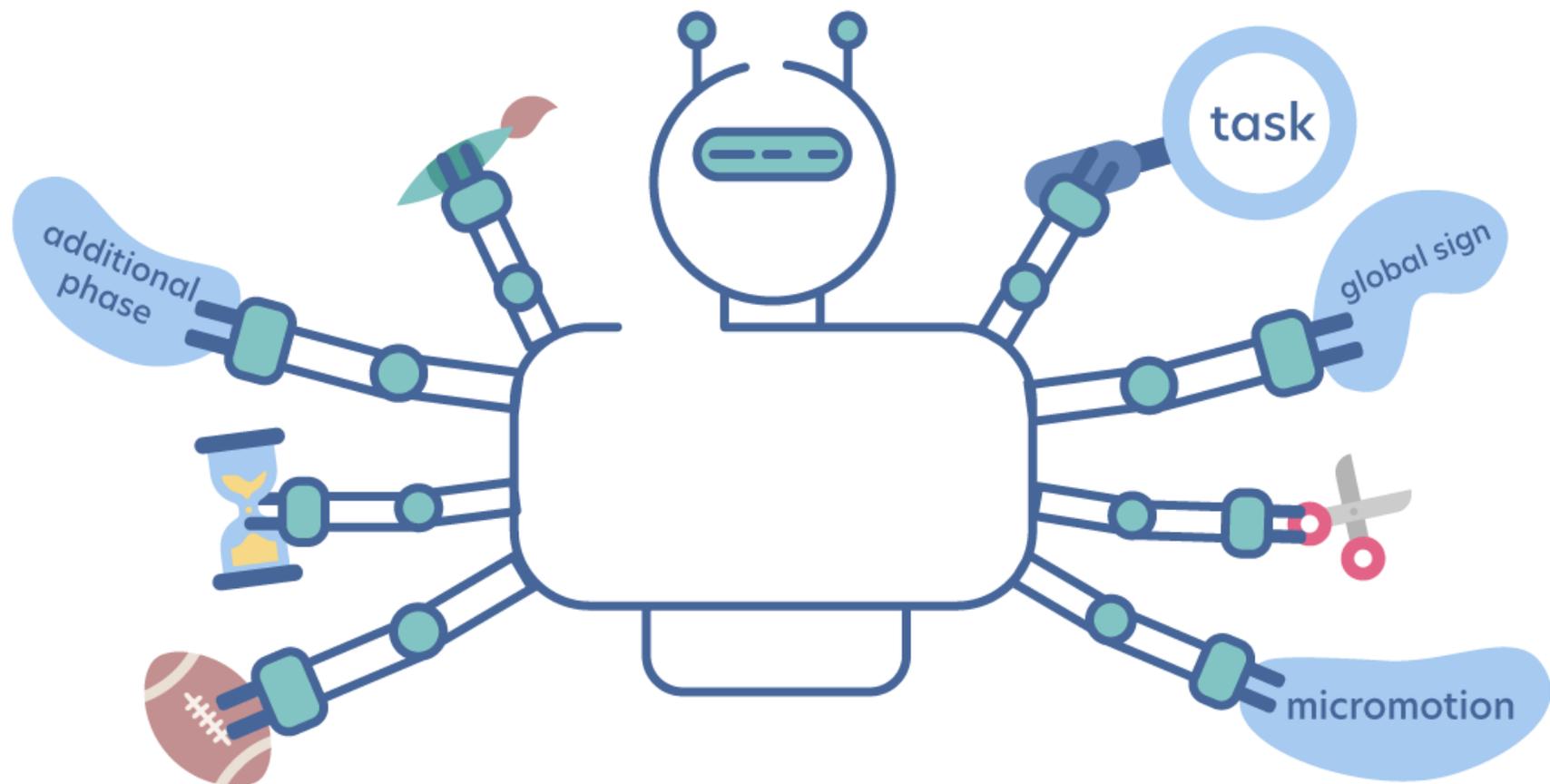
few: $\lambda_i < 0$

$$H_{ij} = \frac{\partial^2 \mathcal{L}(D_{\text{train}}, \boldsymbol{\theta})}{\partial \theta_i \partial \theta_j} \Bigg|_{\boldsymbol{\theta} = \tilde{\boldsymbol{\theta}}}$$



Outline

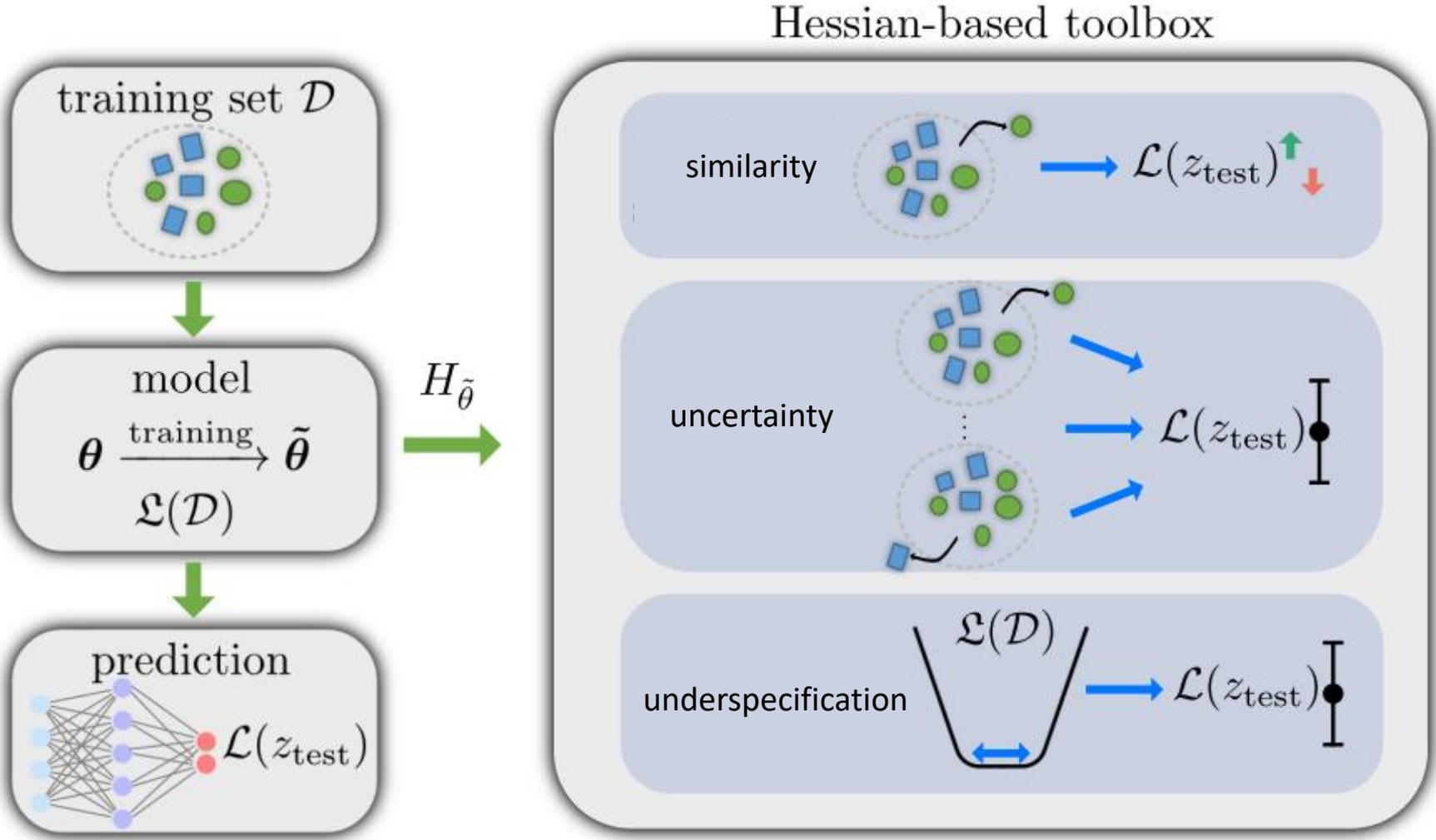
1. Interpreting an ML model
2. Reliability methods



Outline

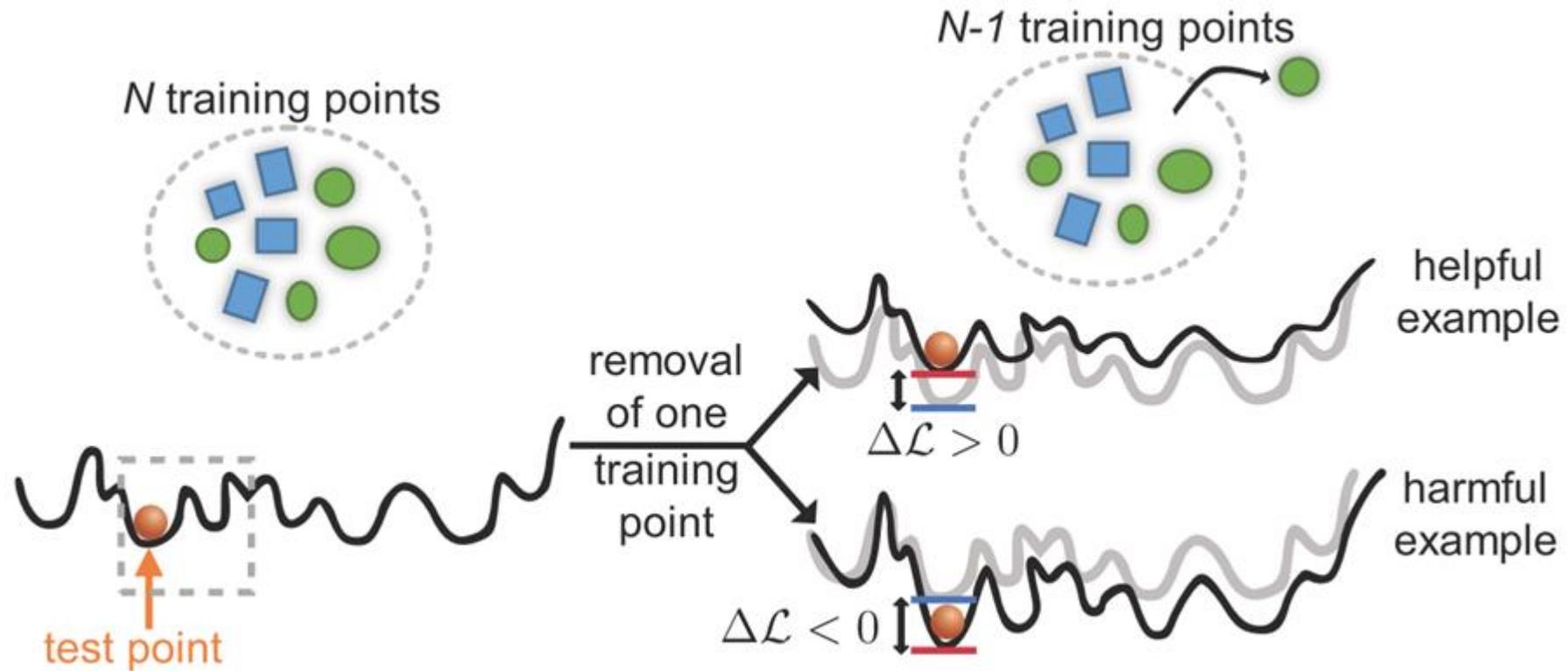
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Hessian-based toolbox

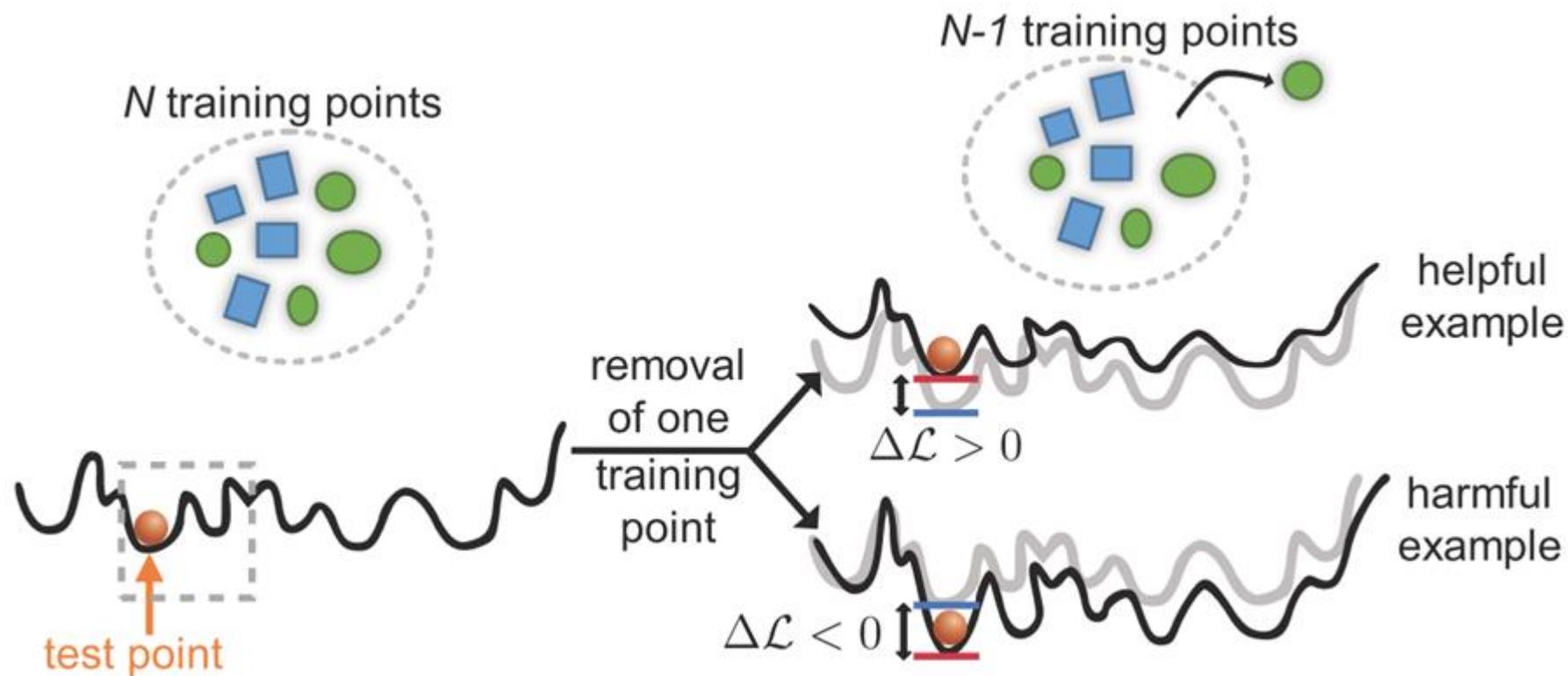


- Influence functions
Koh & Liang
arXiv:1703.04730
- Resampling
Uncertainty
Estimation (RUE)
Schulam & Saria
arXiv:1901.00403
- Local Ensembles
(LEs)
Madras, Atwood, D'Amour
arXiv:1910.09573

Leave-one-out training

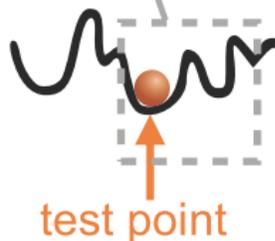
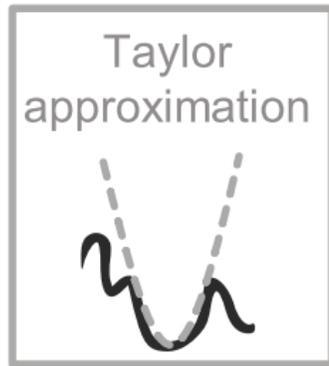


Leave-one-out training



prohibitively expensive!

Influence functions



Analytical approximation for leave-one-out training

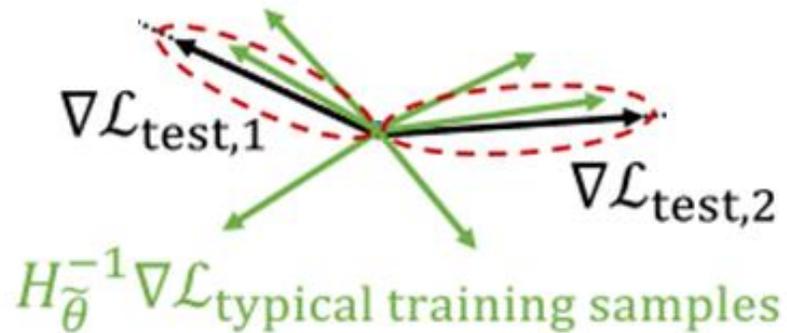
$$\mathcal{I}(z_r, z_{\text{test}}) = \frac{1}{n} \nabla_{\theta} \mathcal{L}(z_{\text{test}}, \hat{\theta})^T \underbrace{H_{\theta}^{-1}(\hat{\theta})}_{\text{approximated change in parameters due to removal of } z_r} \nabla_{\theta} \mathcal{L}(z_r, \hat{\theta})$$

approximated change
in parameters due to
removal of z_r

Assumption: Hessian is positive-definite.

Generalization to non-convex models was done by Koh & Liang: arXiv:1703.04730, ICML 2017's best paper

Geometrical interpretation



**notion of similarity
in the model
internal representation!**

$$\mathcal{I}(z_r, z_{\text{test}}) = \frac{1}{n} \nabla_{\theta} \mathcal{L}(z_{\text{test}}, \hat{\theta})^T H_{\theta}^{-1}(\hat{\theta}) \nabla_{\theta} \mathcal{L}(z_r, \hat{\theta})$$

it is a scalar product of gradient of a test point and the gradient of a training point, corrected by local curvature described by the Hessian

Three messages



Detection additional phases



Detecting influential
data features



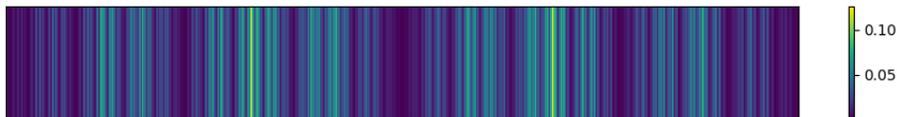
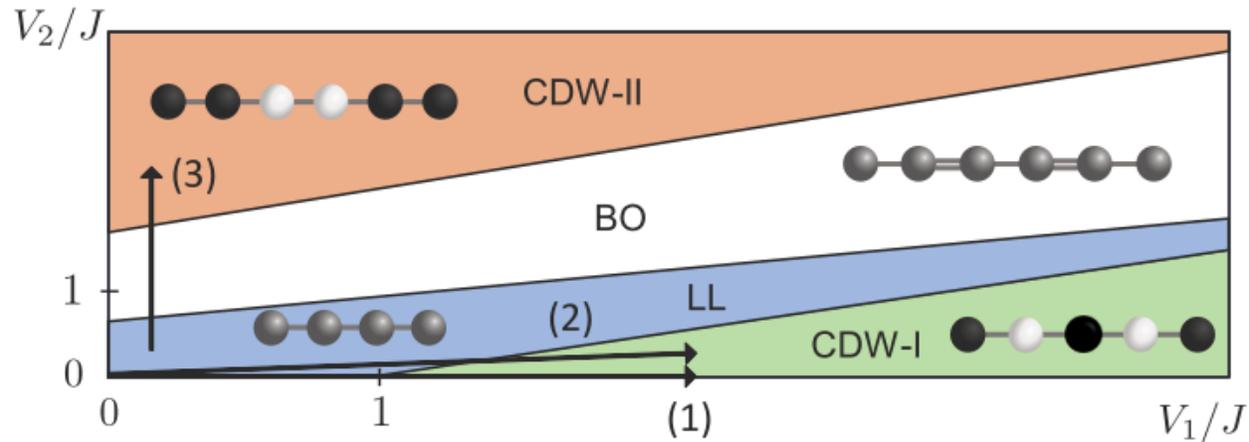
Anomaly detection
with influence functions

Physical input data

1) simulated

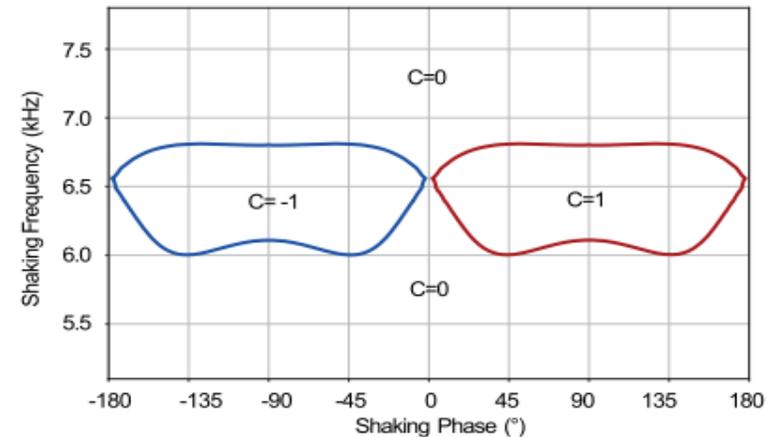
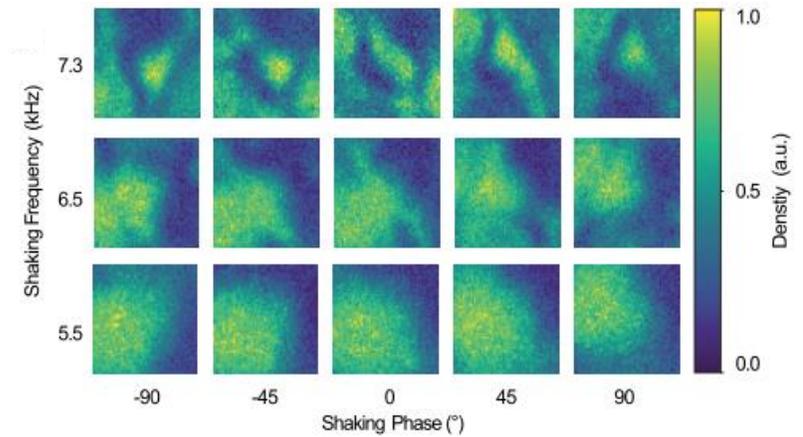
spinless 1D Fermi-Hubbard model at half-filling

$$\hat{H} = -J \sum_{\langle i,j \rangle} c_i^\dagger c_j + V_1 \sum_{\langle i,j \rangle} n_i n_j + V_2 \sum_{\langle\langle i,j \rangle\rangle} n_i n_j$$



2) experimental

topological Haldane model



Three messages



Detection additional phases

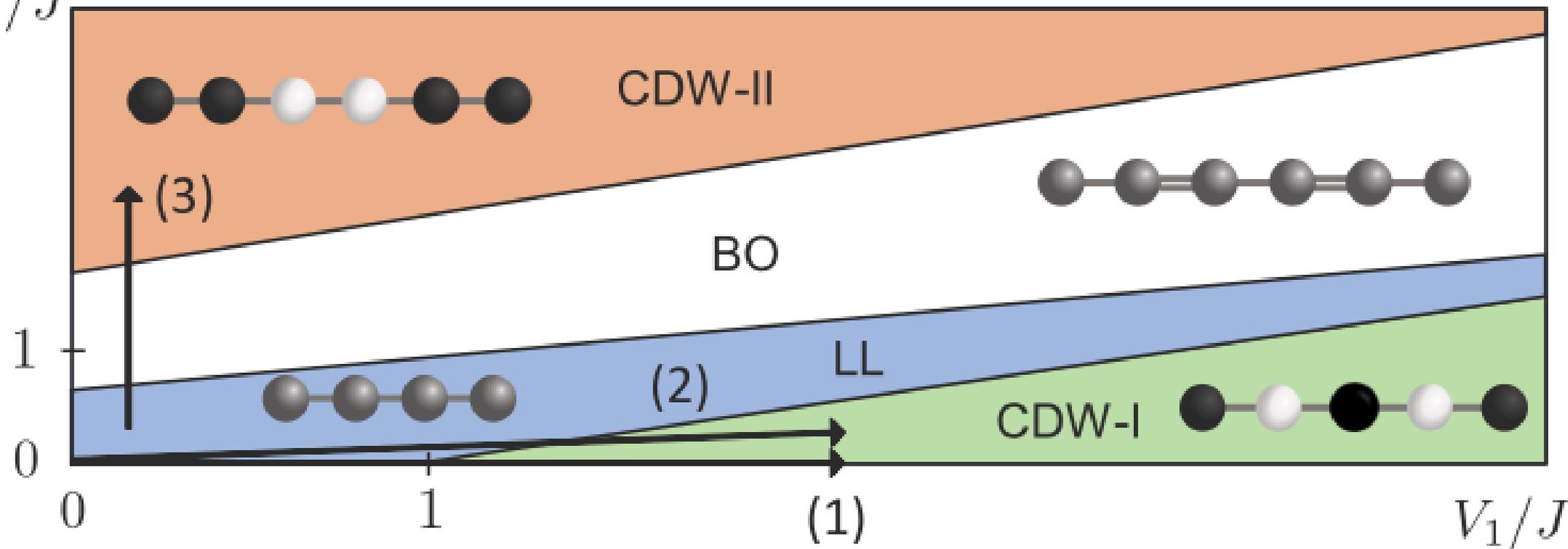


Detecting influential
data features



Anomaly detection
with influence functions

V_2/J

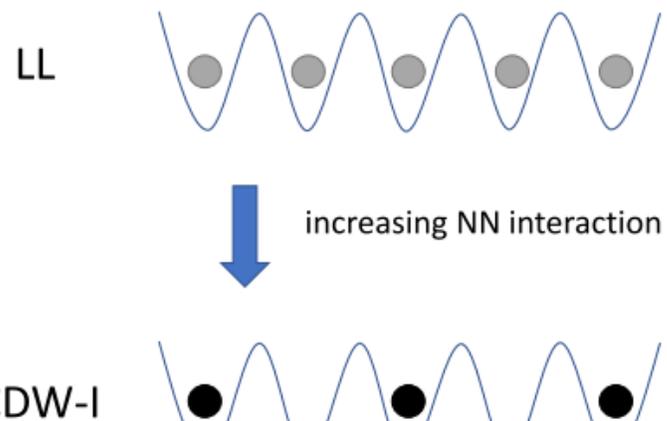
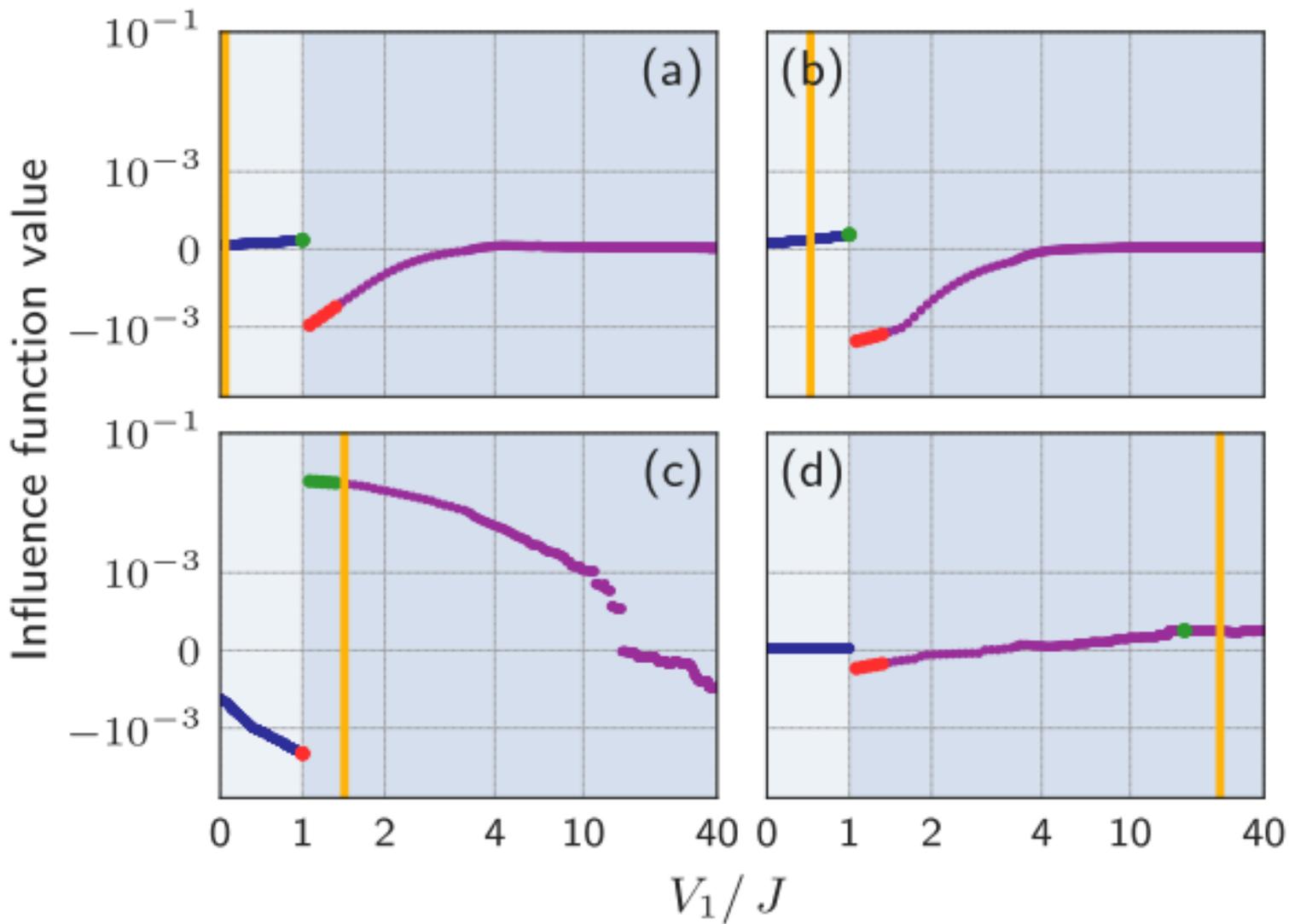


V_1/J

— test point

— training points
from LL phase

— training points
from CDW-I phase



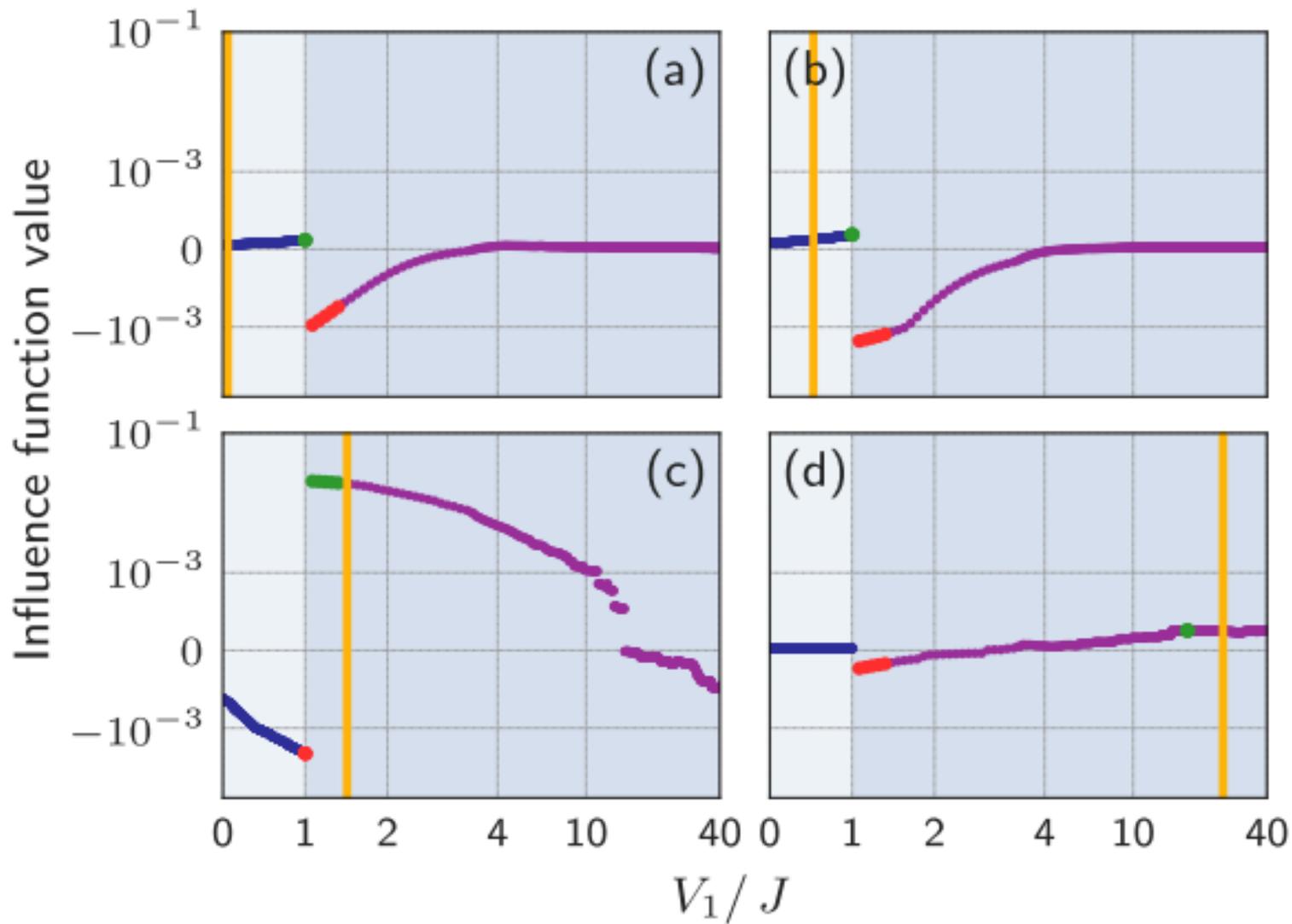
nearest neighbor interaction / hopping amplitude

A. Dawid et al, *New J. Phys.* **22** 115001 (2020)

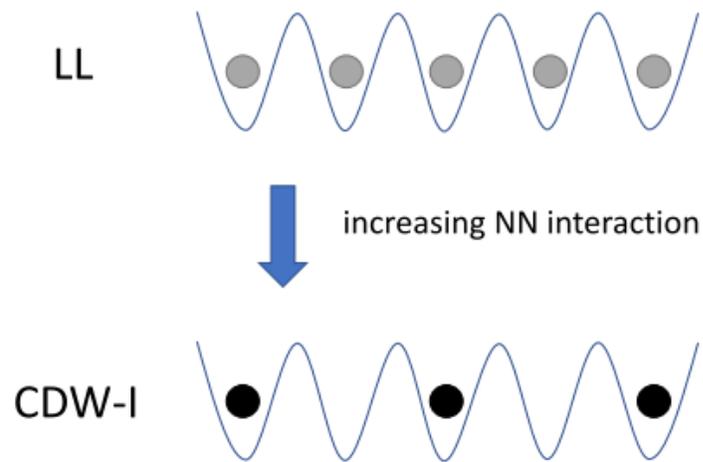
— test point

— training points from LL phase

— training points from CDW-I phase

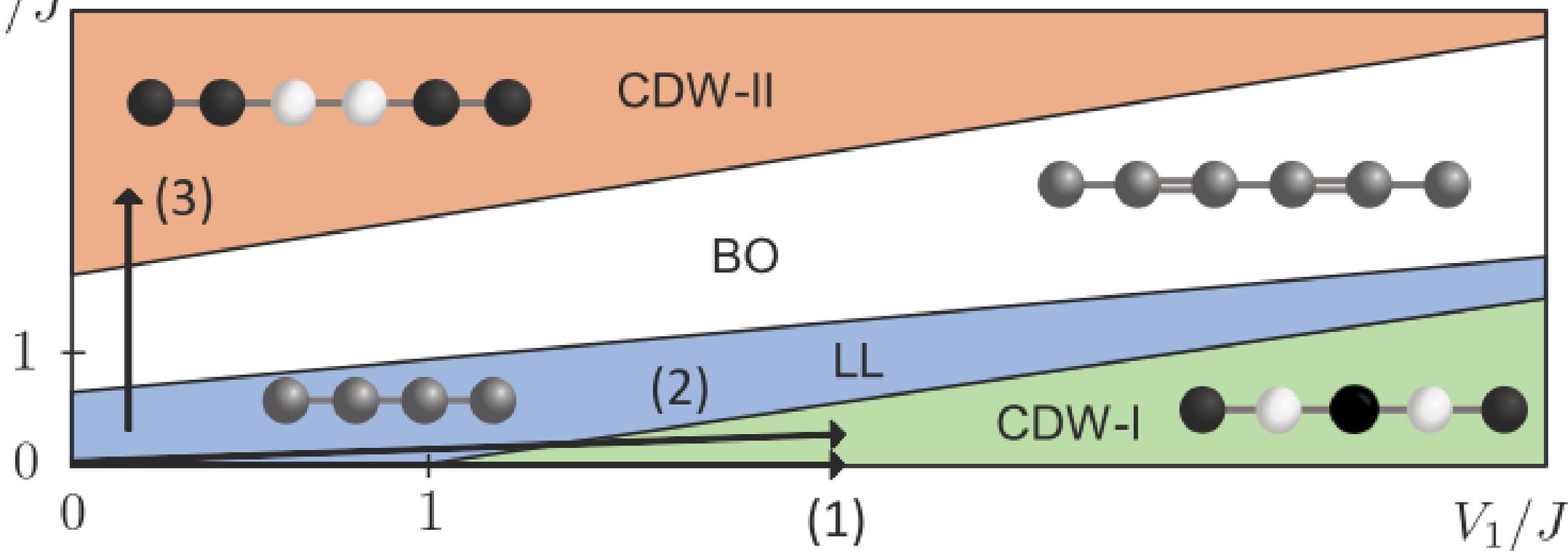


nearest neighbor interaction / hopping amplitude



It learns sth related to order parameter!

V_2/J

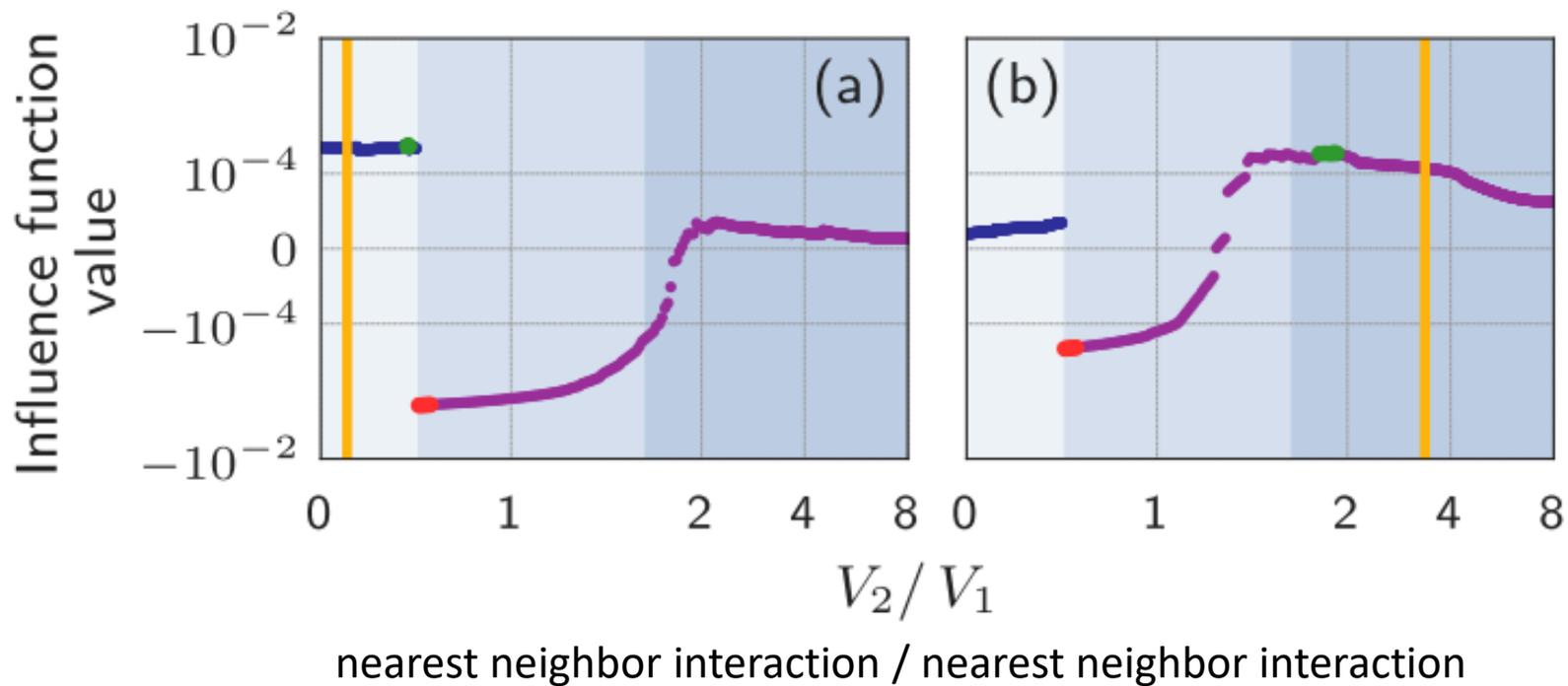


V_1/J

— test point

— training points
from LL phase

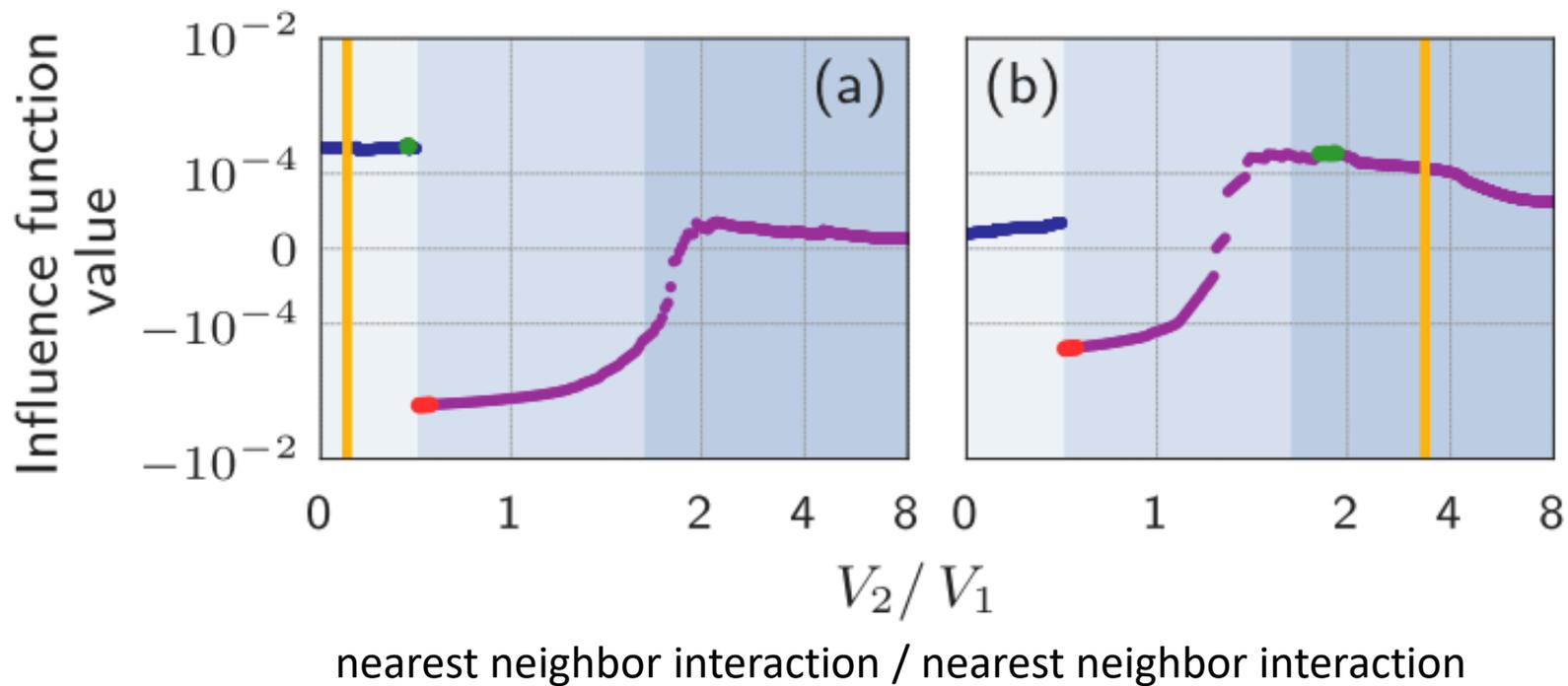
— training points
from BO
and CDW-II phases



— test point

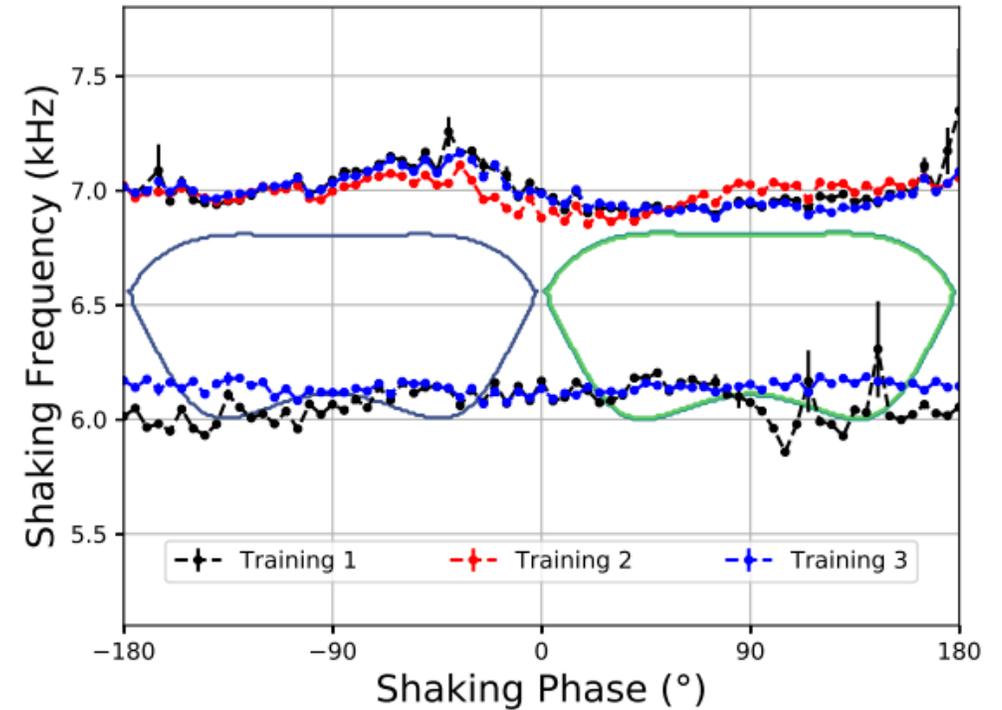
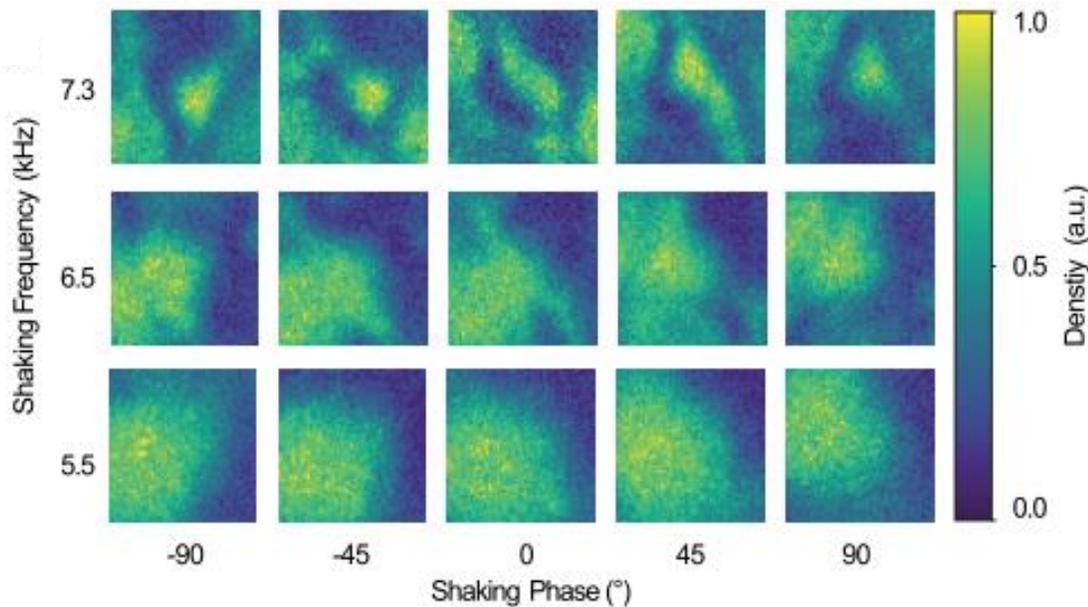
— training points
from LL phase

— training points
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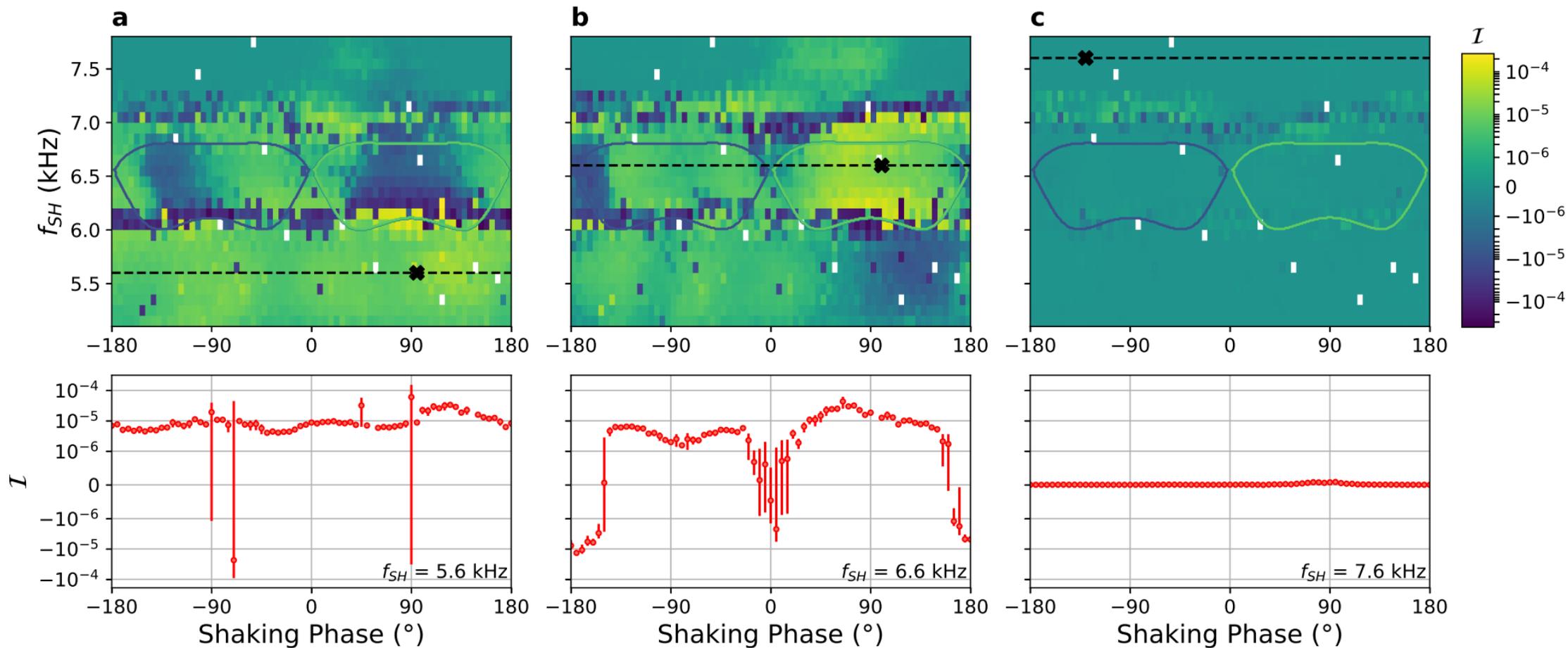


It sees additional phase!

Unsupervised machine learning of topological phase transition from experimental data



unsupervised approaches had troubles with distinguishing between two topological phases...



Three messages



Detection additional phases

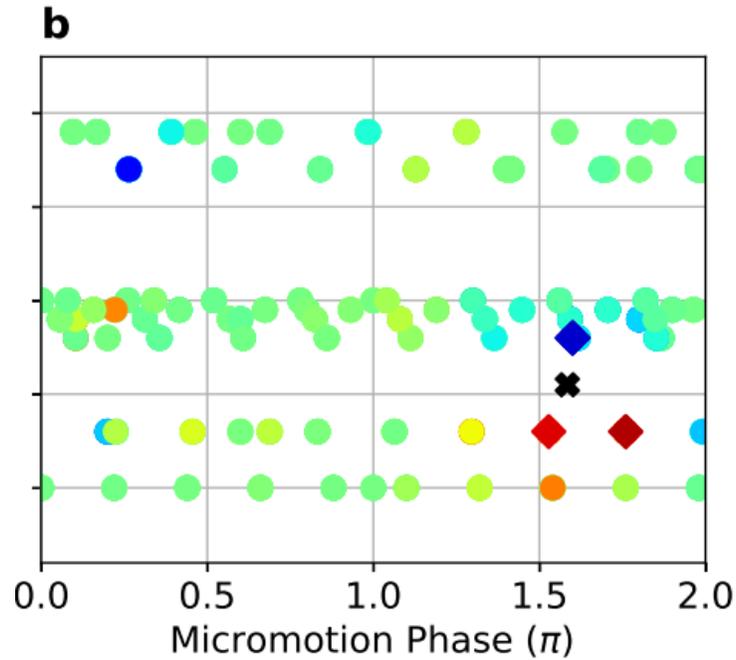


Detecting influential
data features

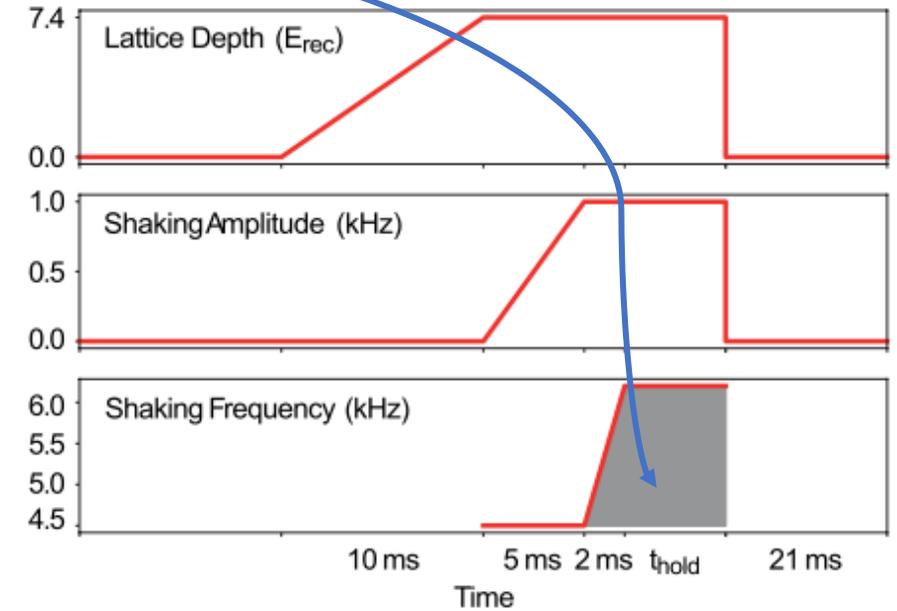


Anomaly detection
with influence functions

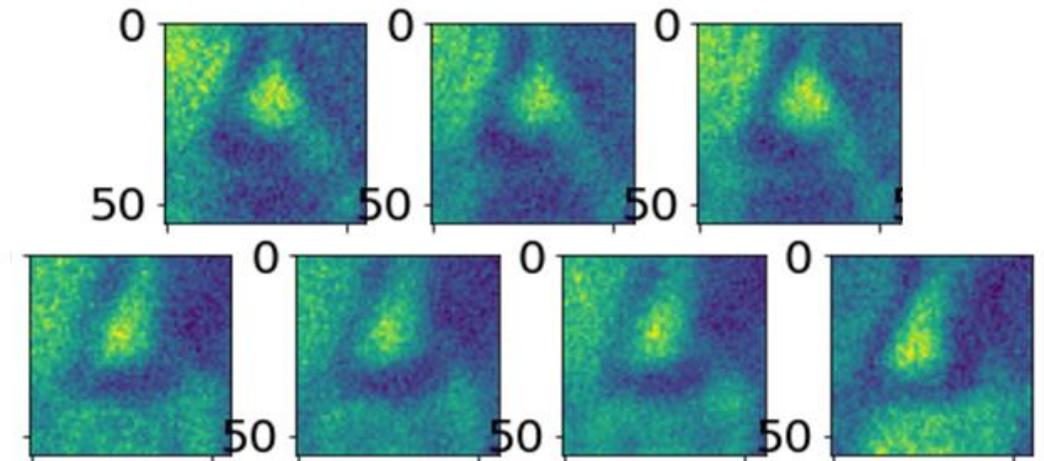
Micromotion phase



The most influential points are localized around the same micromotion phase as test point



Same shaking frequency and shaking phase
different micromotion phases



Three messages



Detection additional phases



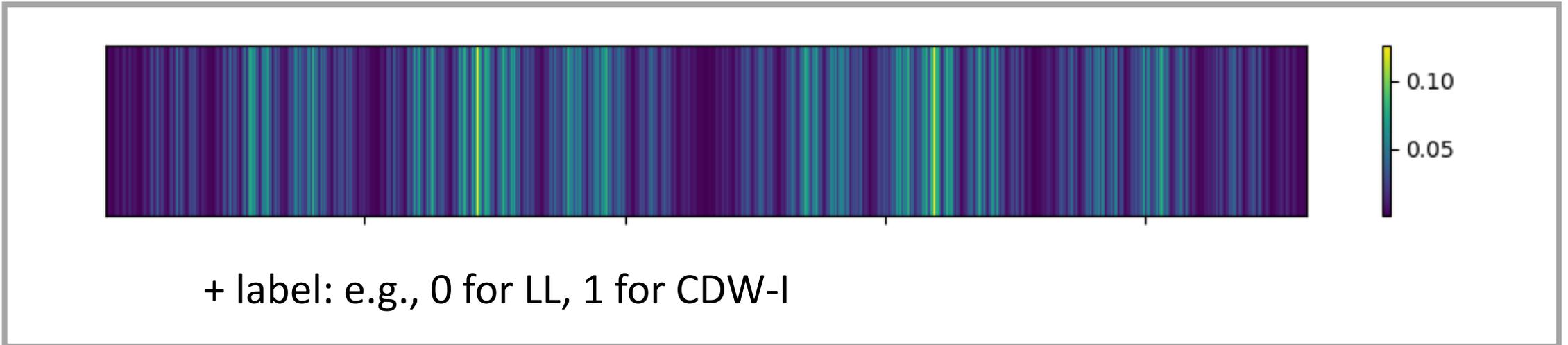
Detecting influential
data features



Anomaly detection
with influence functions

Global sign

What machine gets



We usually fix the global sign to +
Choice of global sign changes nothing in physics

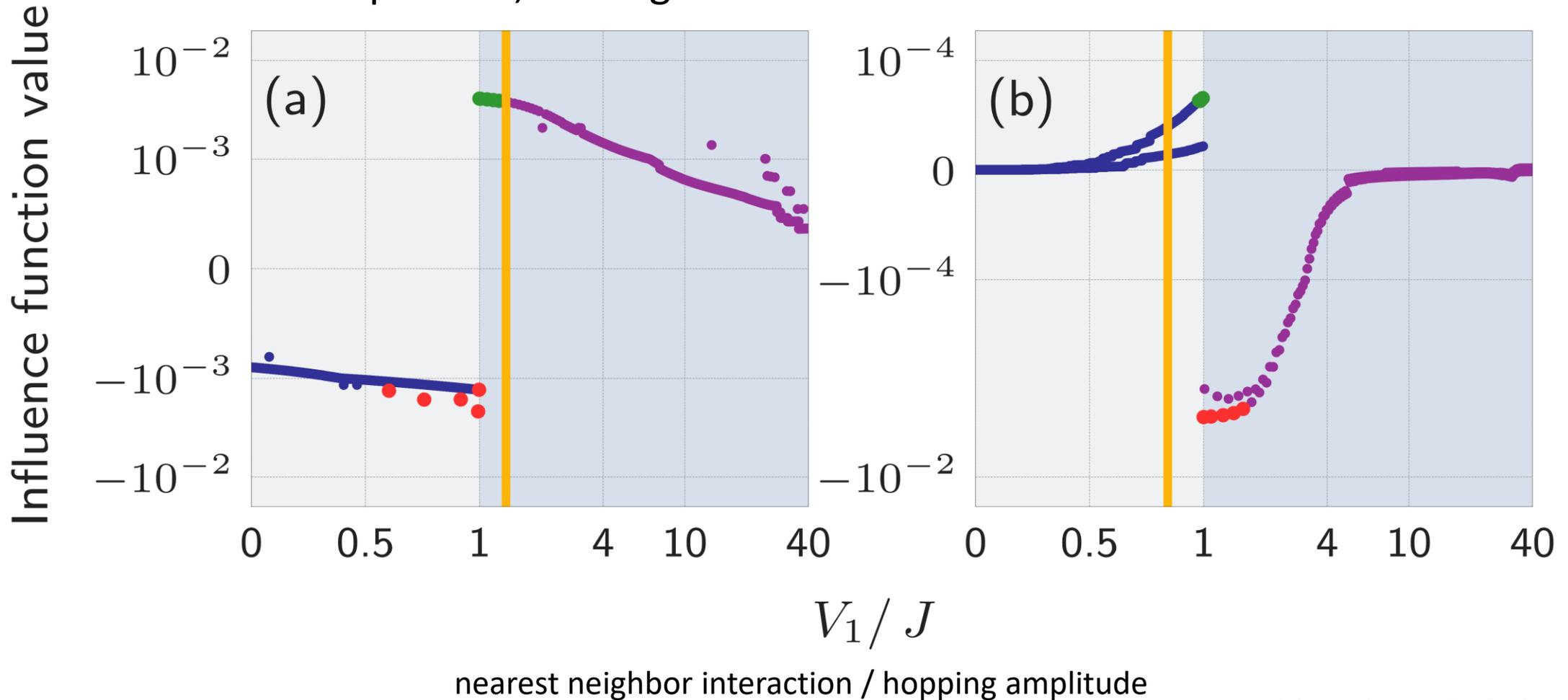
— test point

— training points
from LL phase

— training points
from CDW-I phase

global sign-imbalanced set
98% positive, 2% negative

global sign-balanced set
50% positive, 50% negative



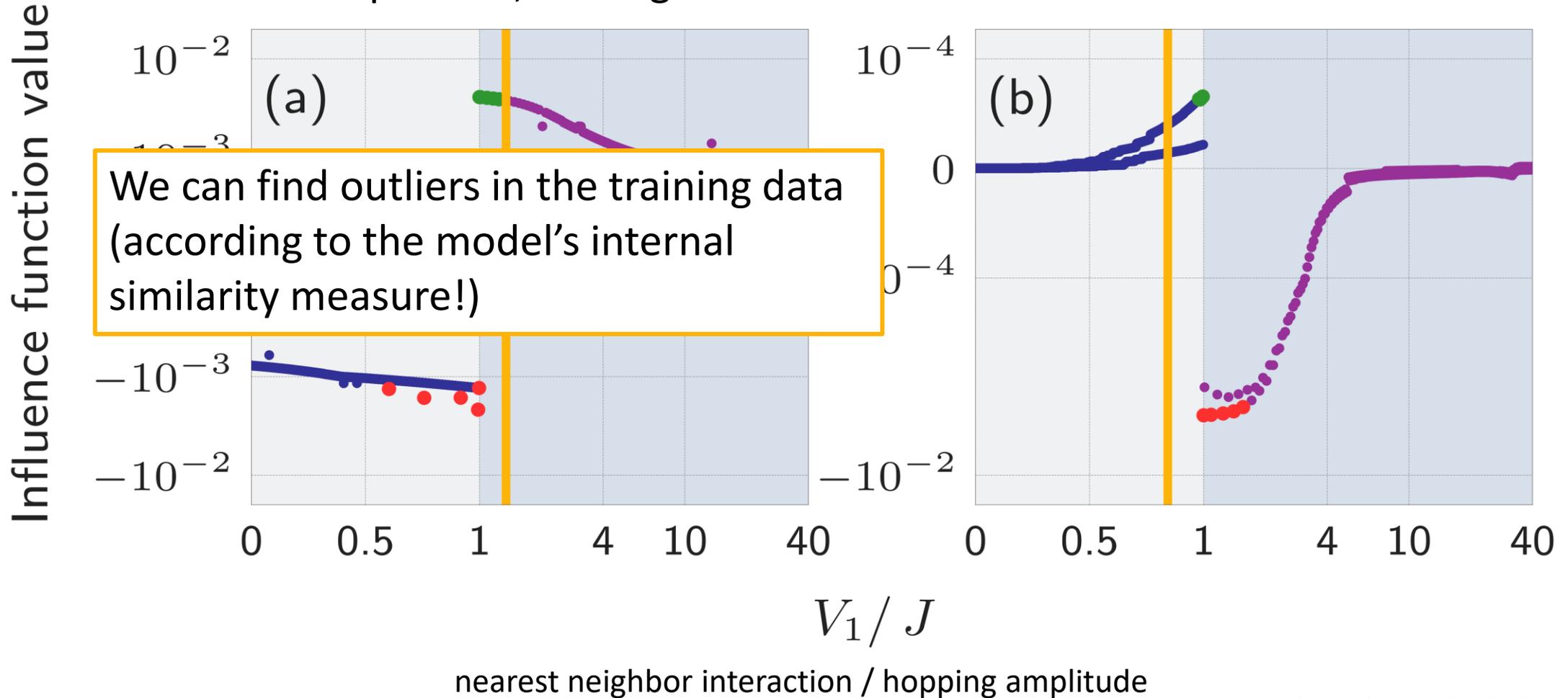
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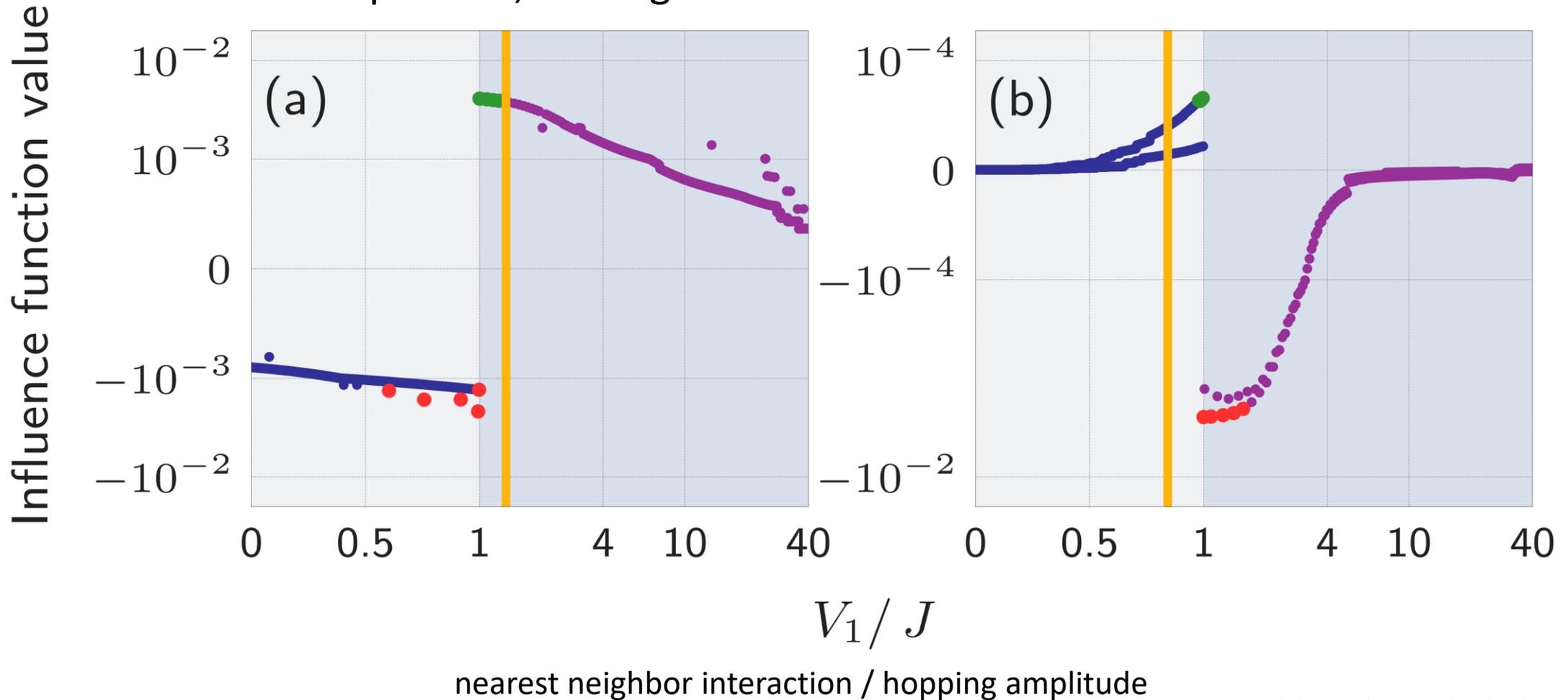
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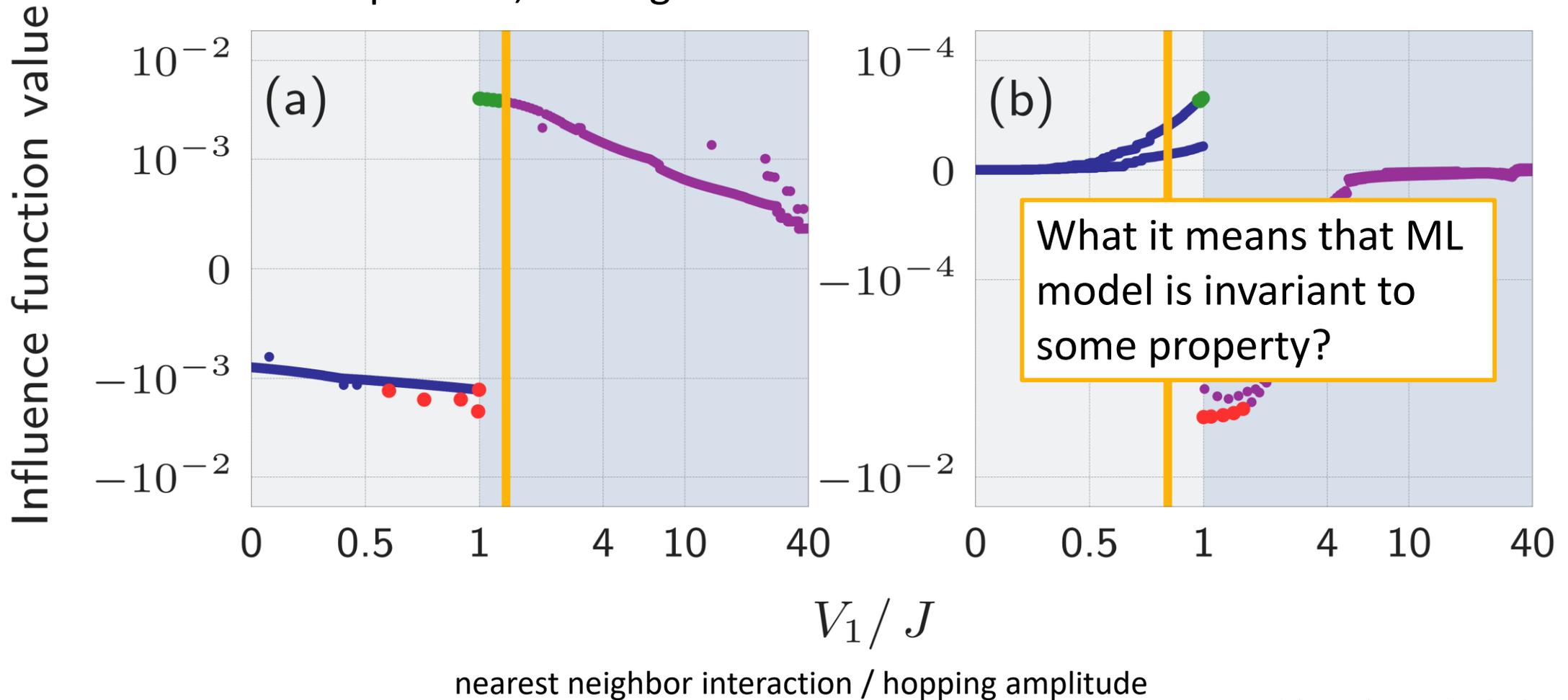
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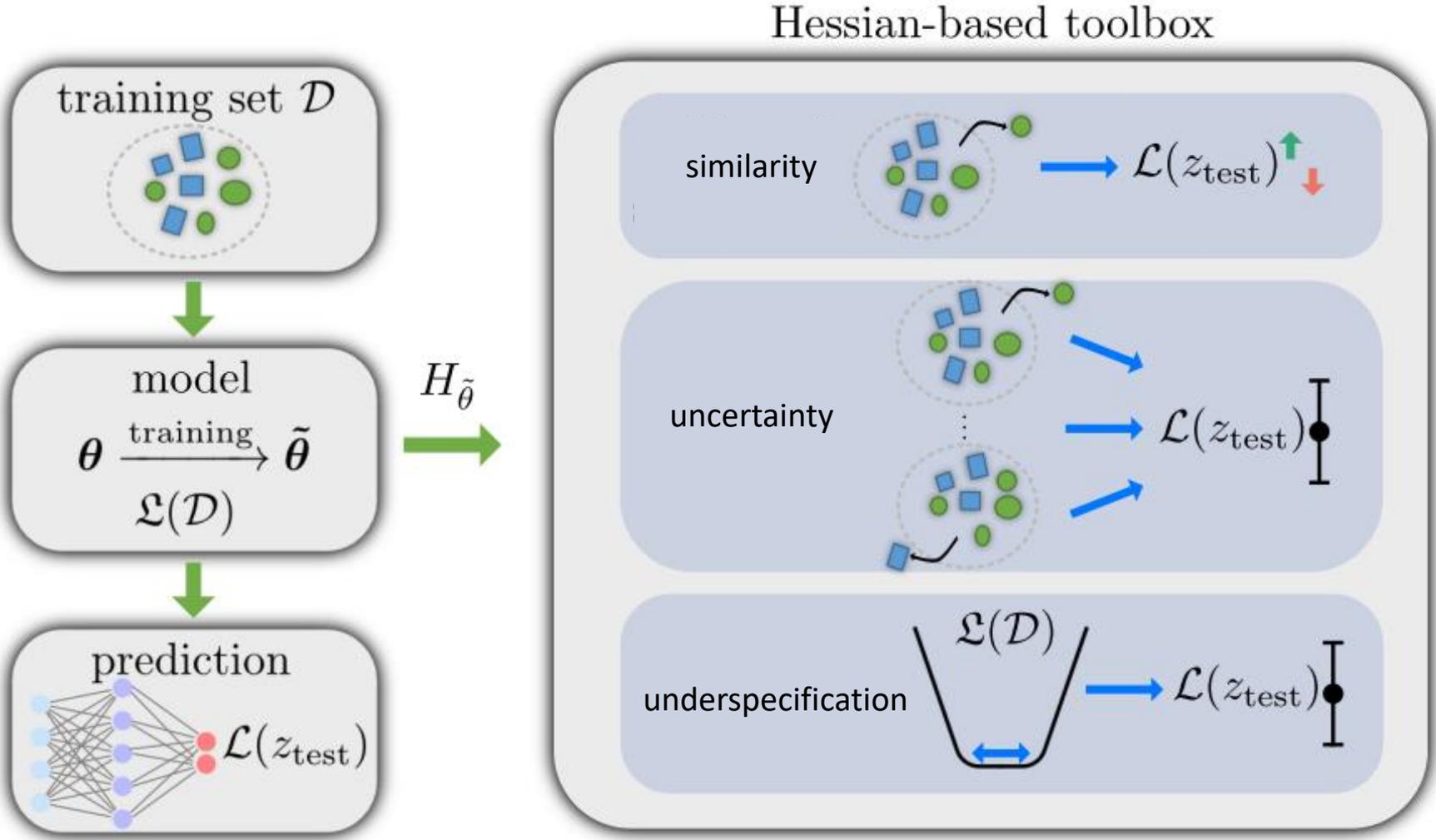
global sign-balanced set
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Outline

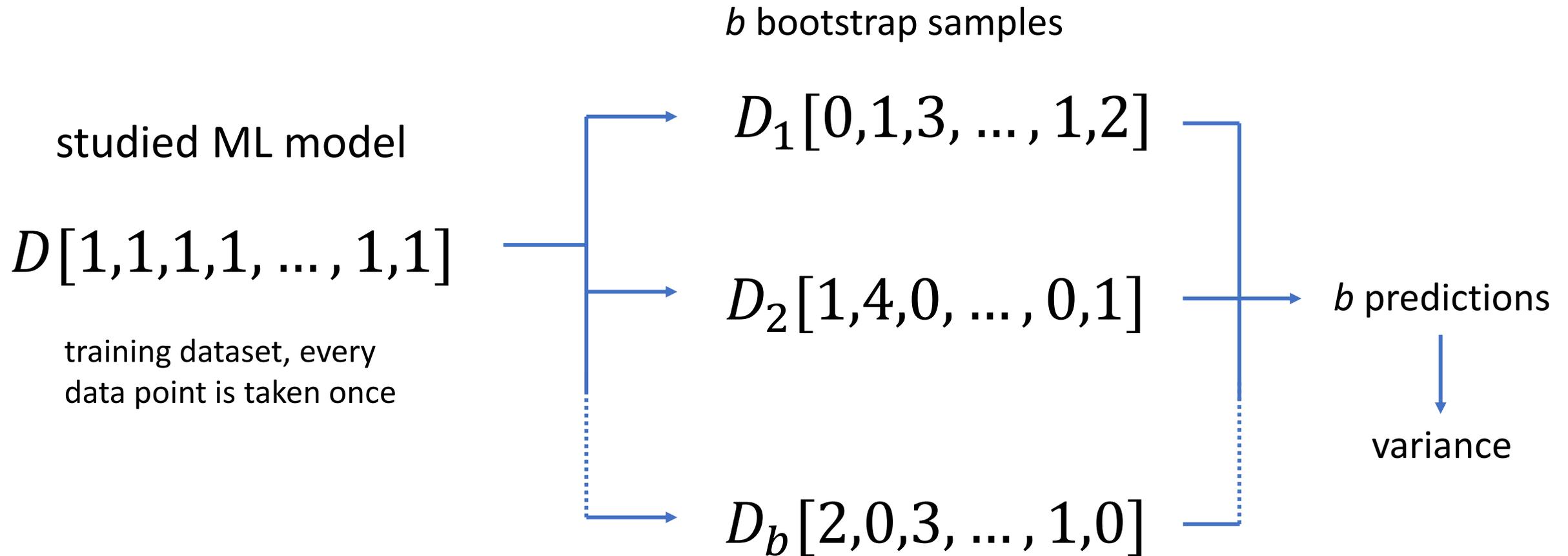
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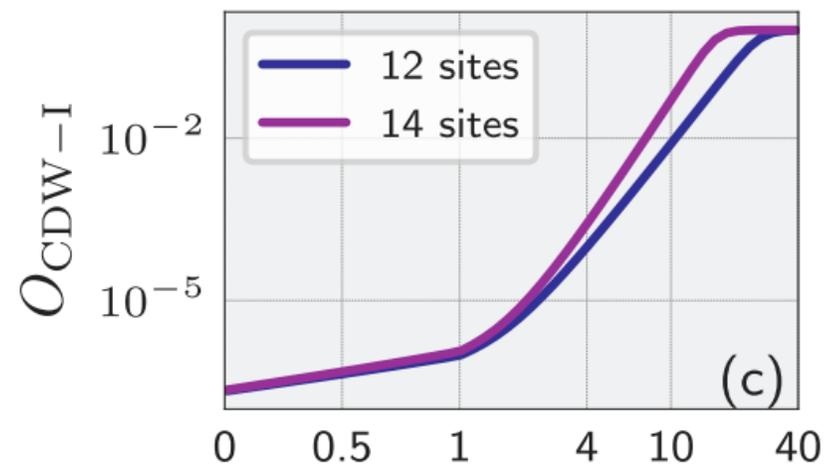
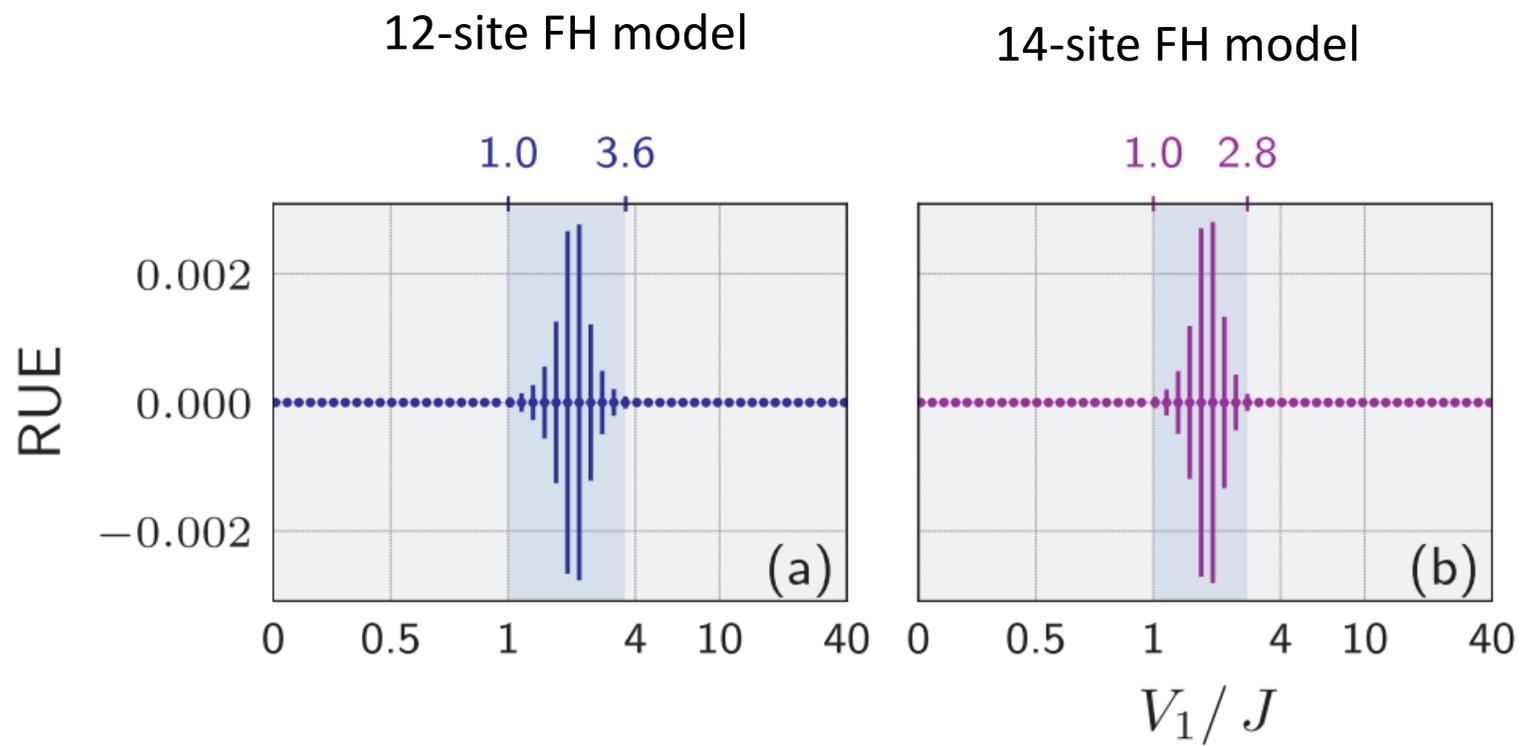
Hessian-based toolbox

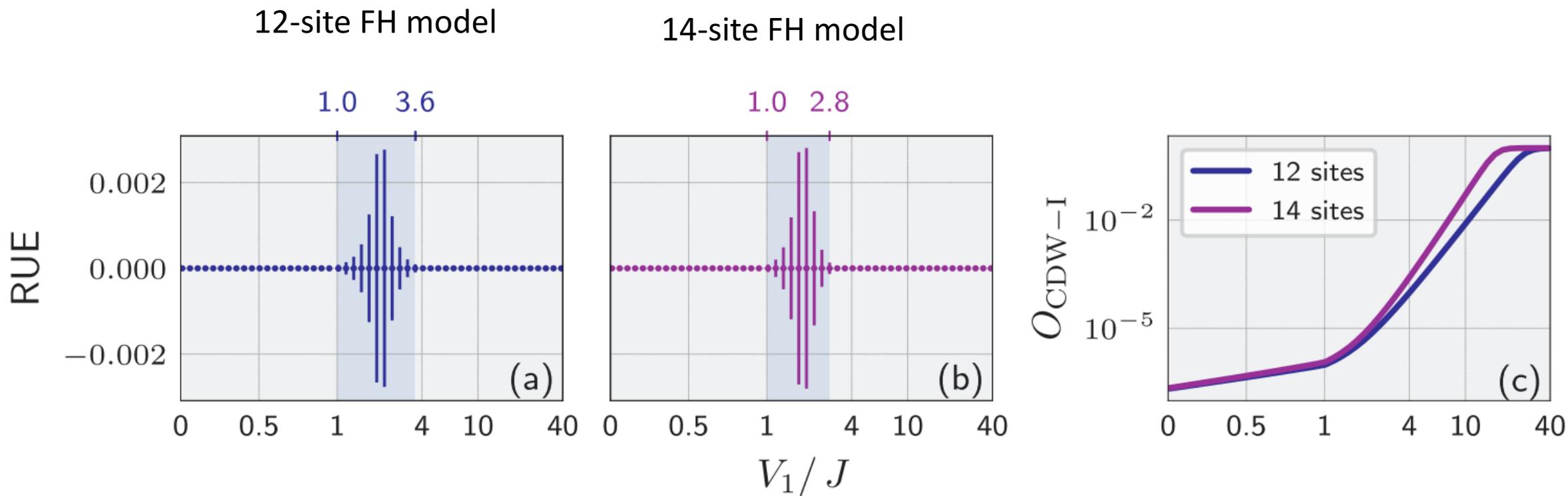


- Influence functions
Koh & Liang
arXiv:1703.04730
- Resampling
Uncertainty
Estimation (RUE)
Schulam & Saria
arXiv:1901.00403
- Local Ensembles
(LEs)
Madras, Atwood, D'Amour
arXiv:1910.09573

Resampling Uncertainty Estimation (RUE)

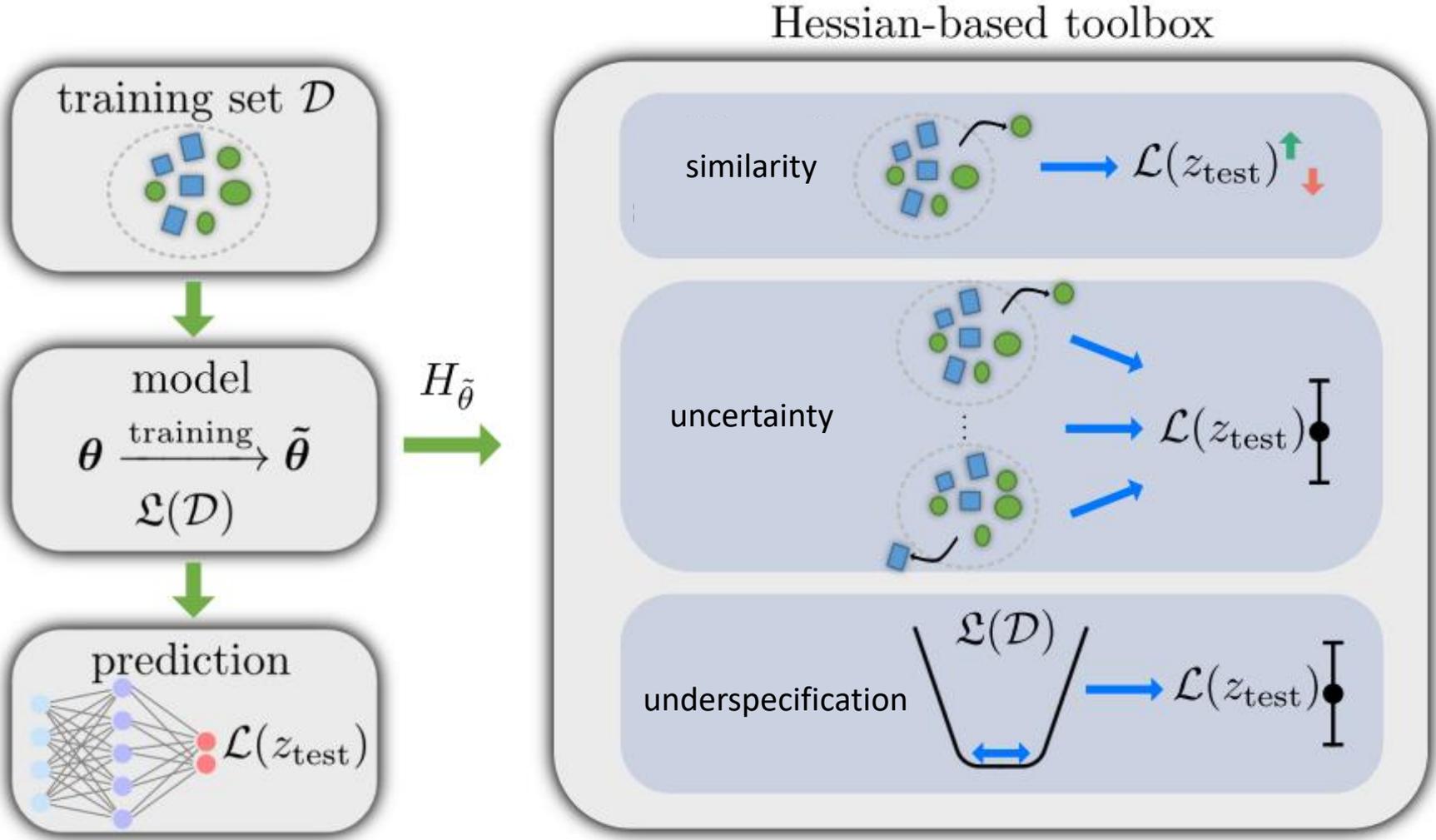






RUE indicates sharpness of the transition

Hessian-based toolbox

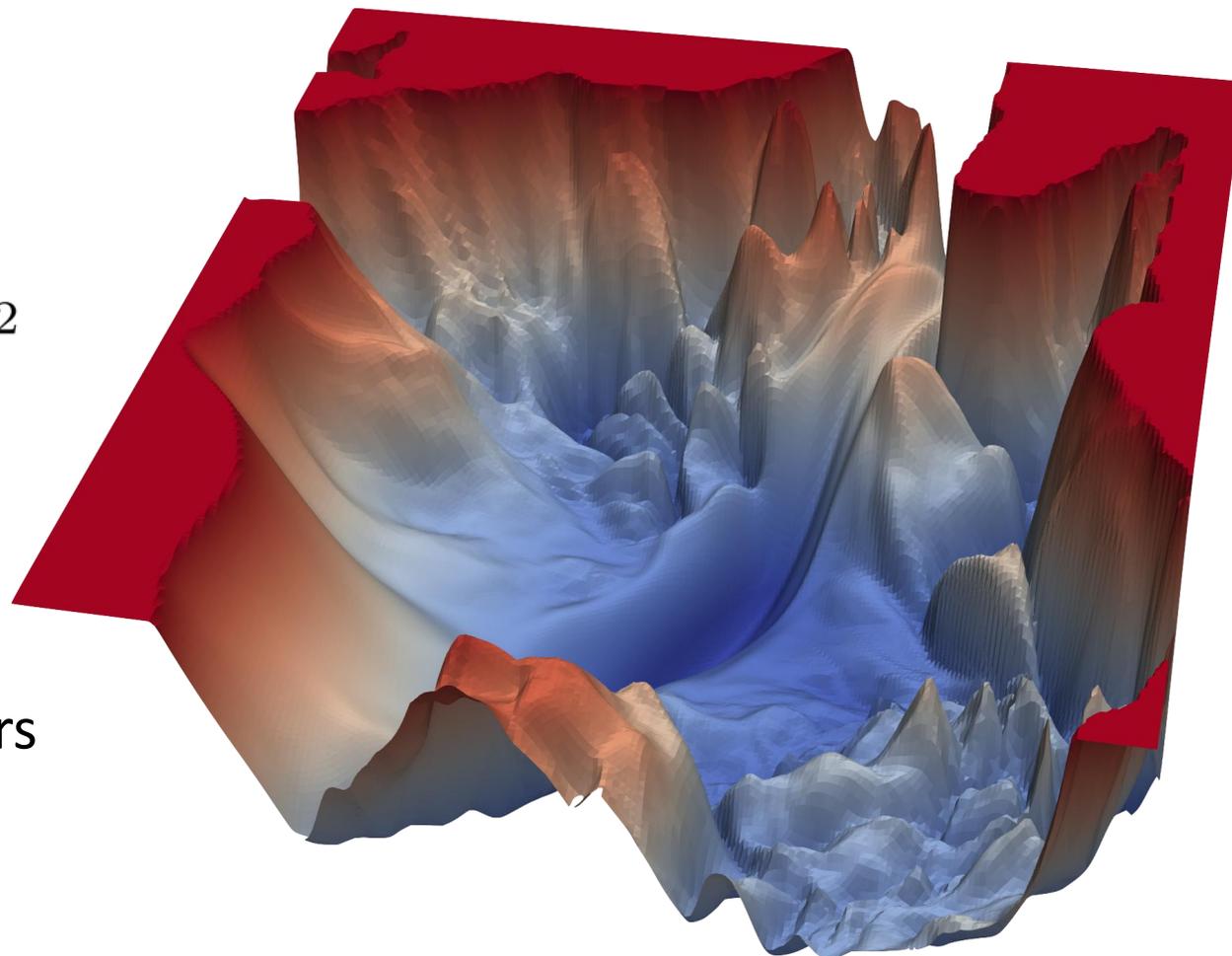


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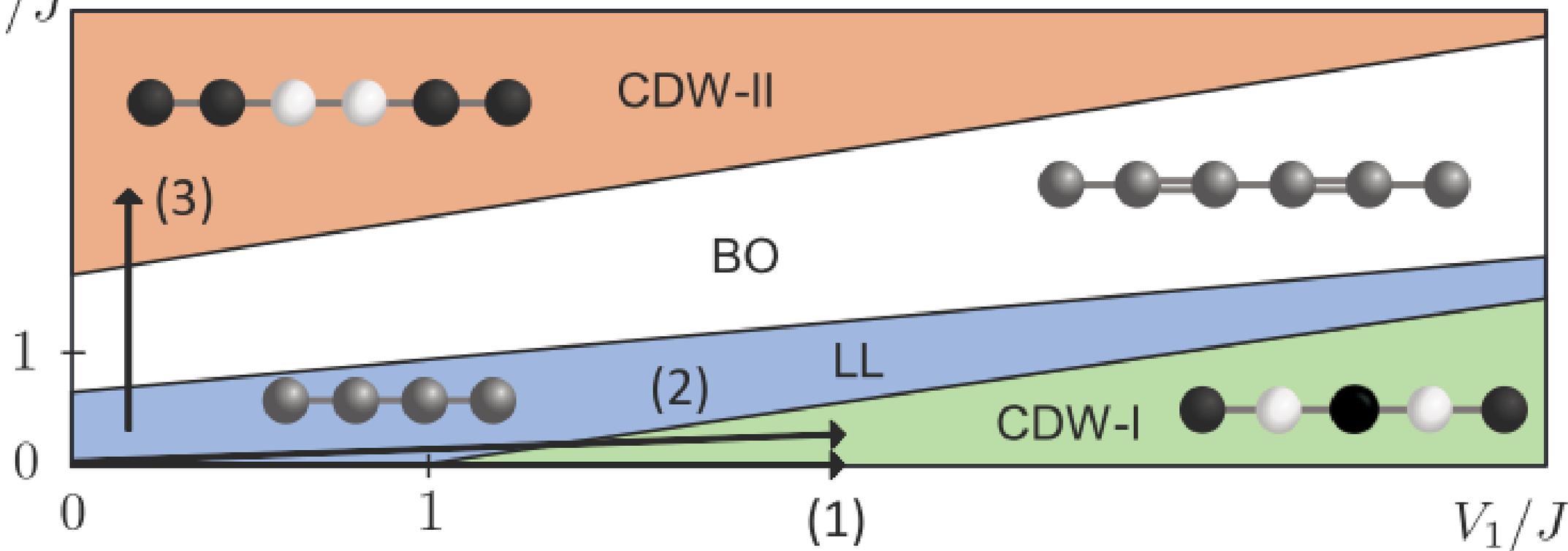
Local-Ensemble-based Extrapolation Score (LEES)

$$\mathcal{E}_m(x_{\text{test}}) = \left\| U_m^\top \nabla_{\theta} \mathcal{L}(z_{\text{test}}, \tilde{\theta}) \right\|_2$$

matrix of $(M - m)$ Hessian eigenvectors
spanning a subspace of low curvature

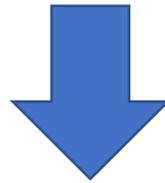
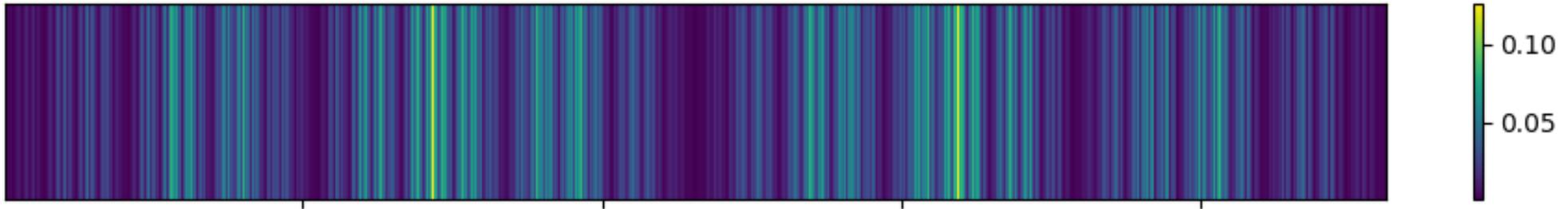


V_2/J



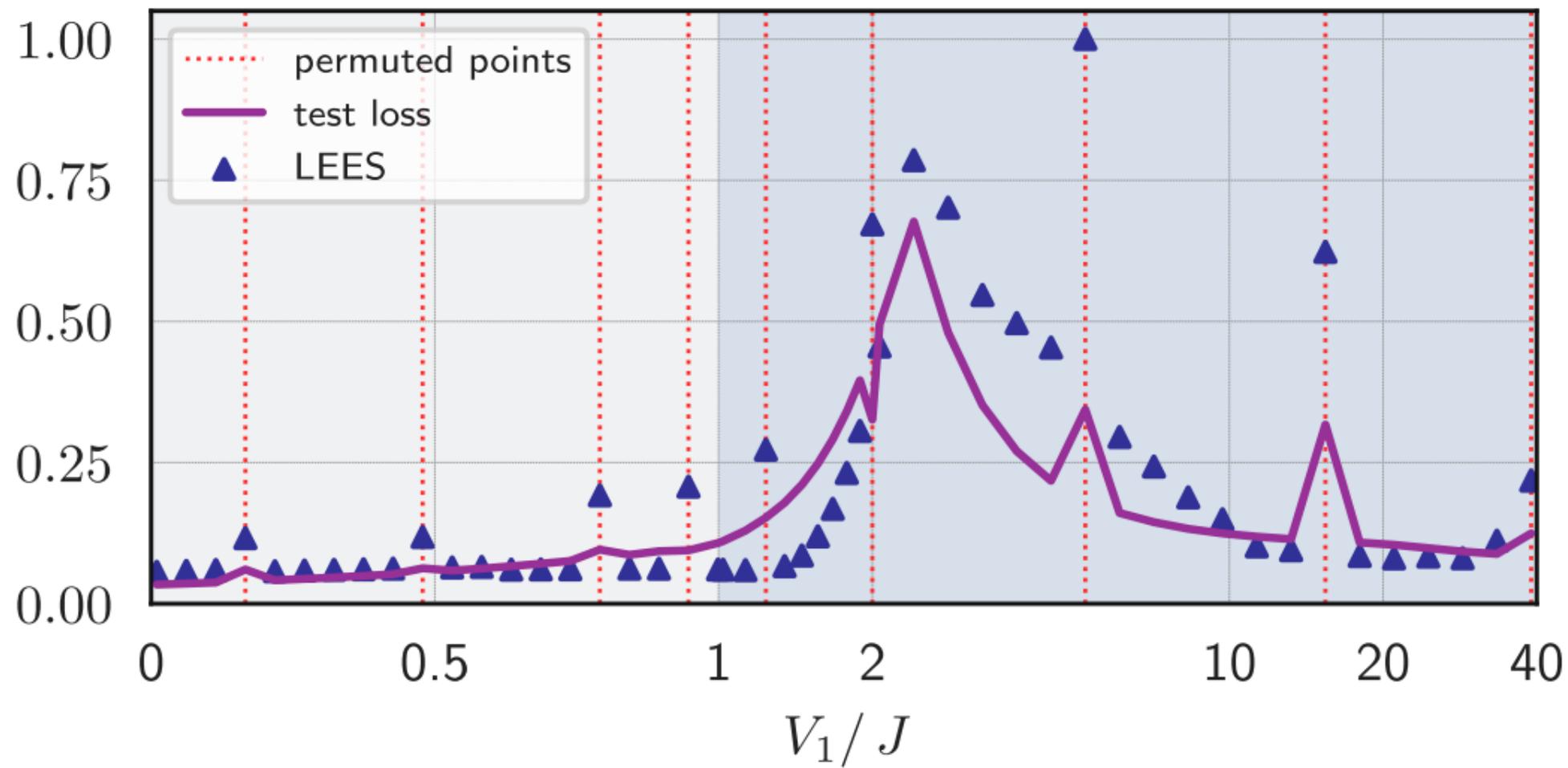
V_1/J

Out-Of-Distribution (OOD) test points

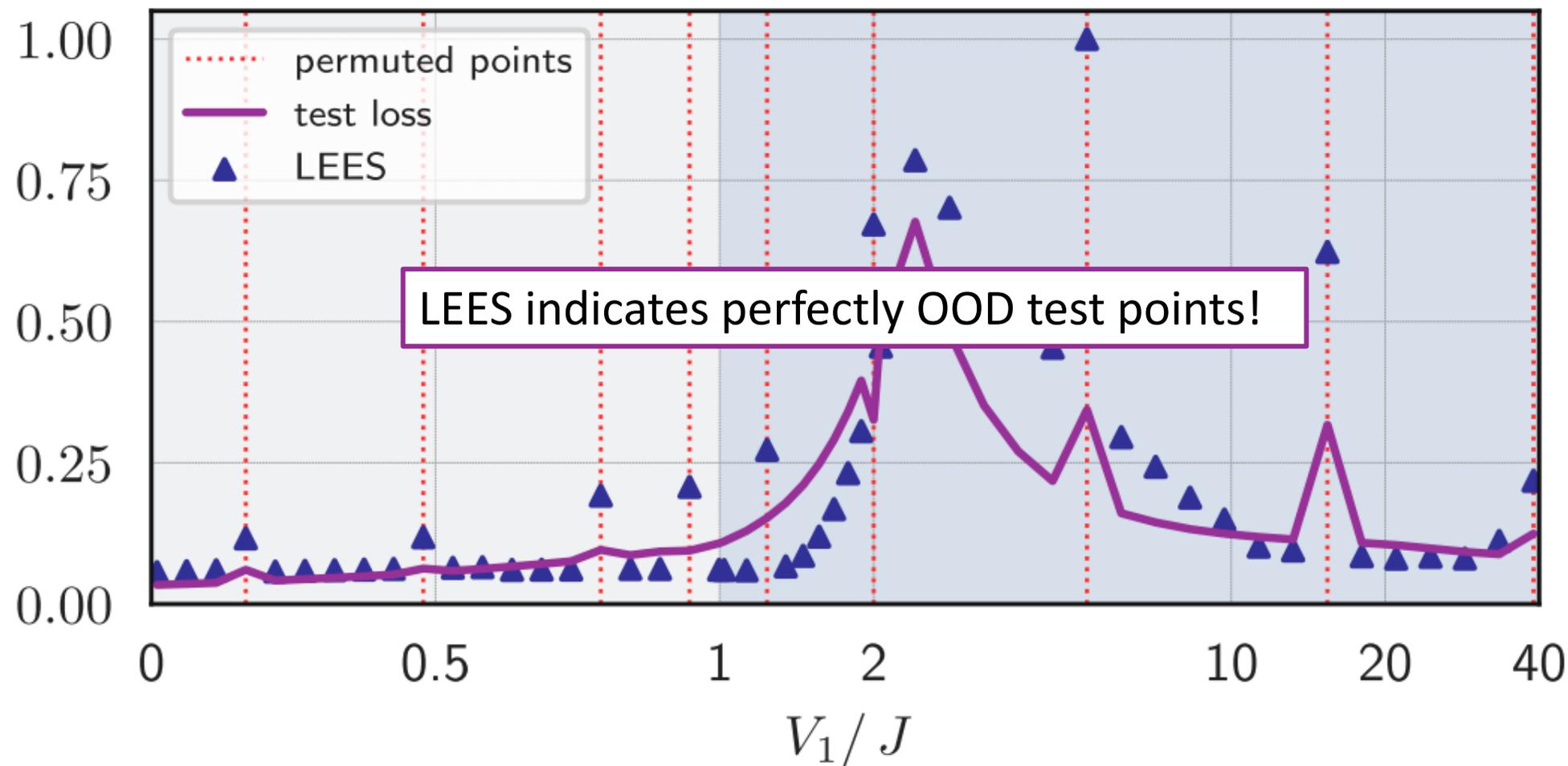


random permutation of eigenvector elements

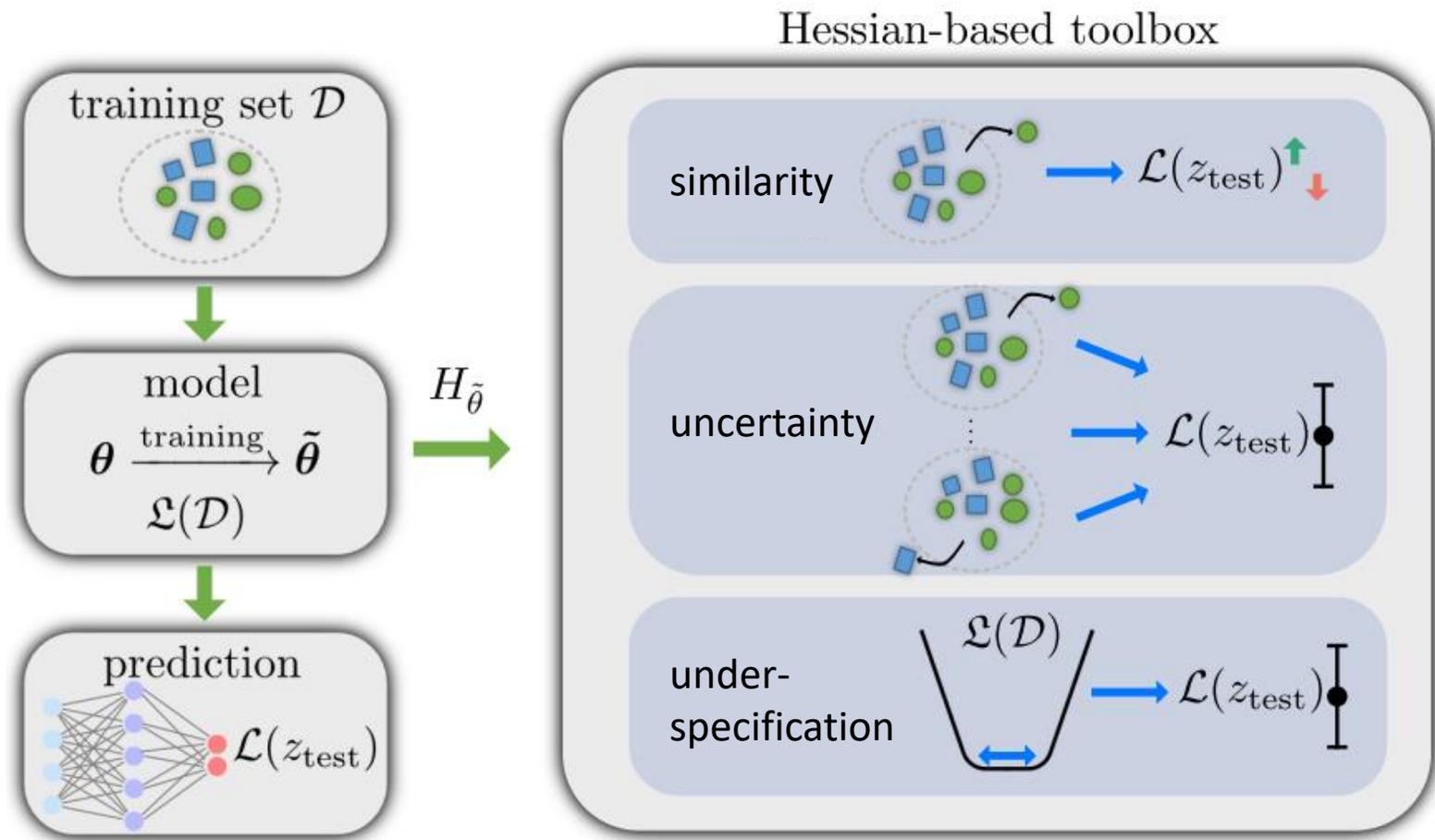
Local Ensemble-based Extrapolation Score

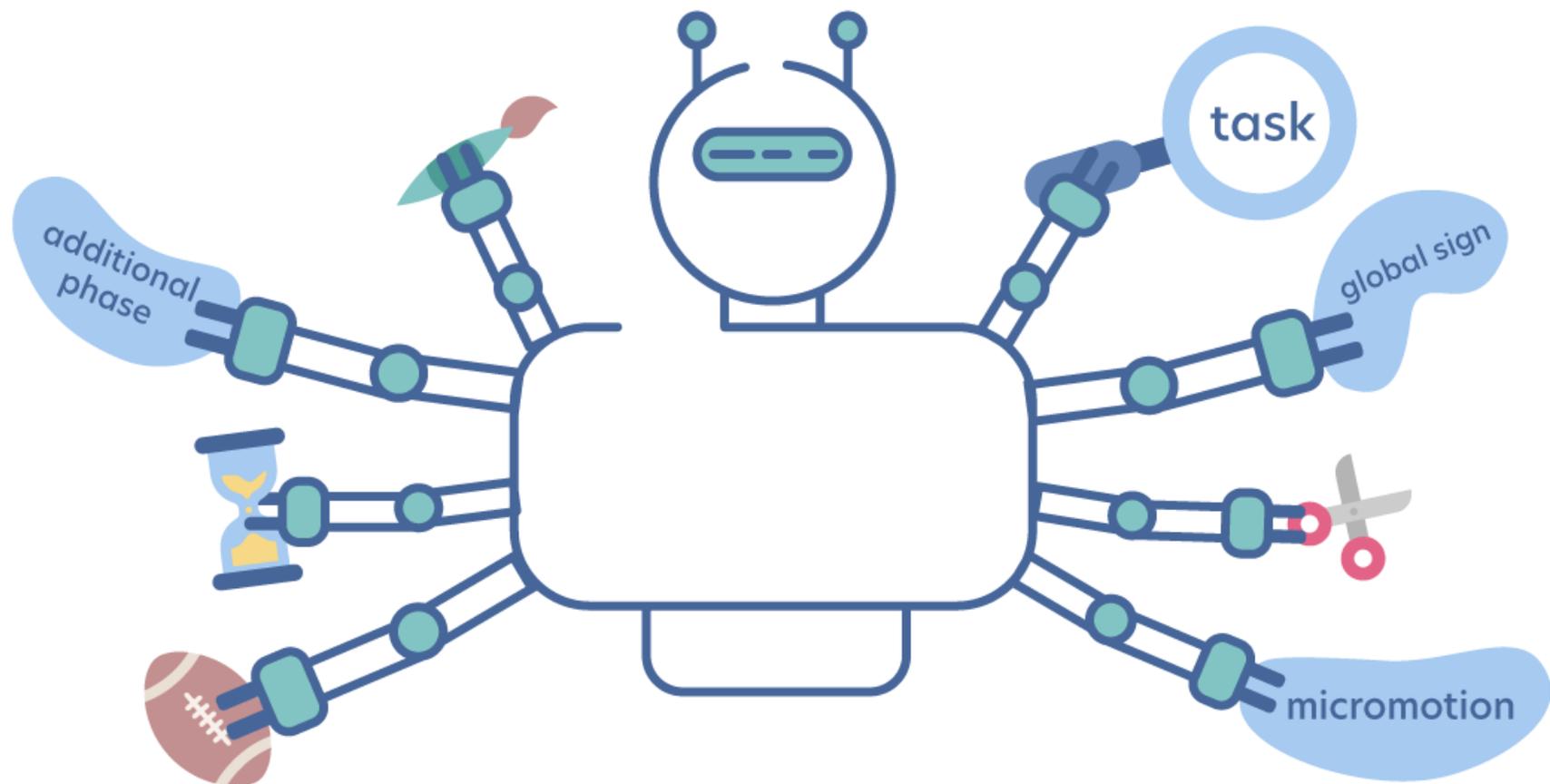


Local Ensemble-based Extrapolation Score

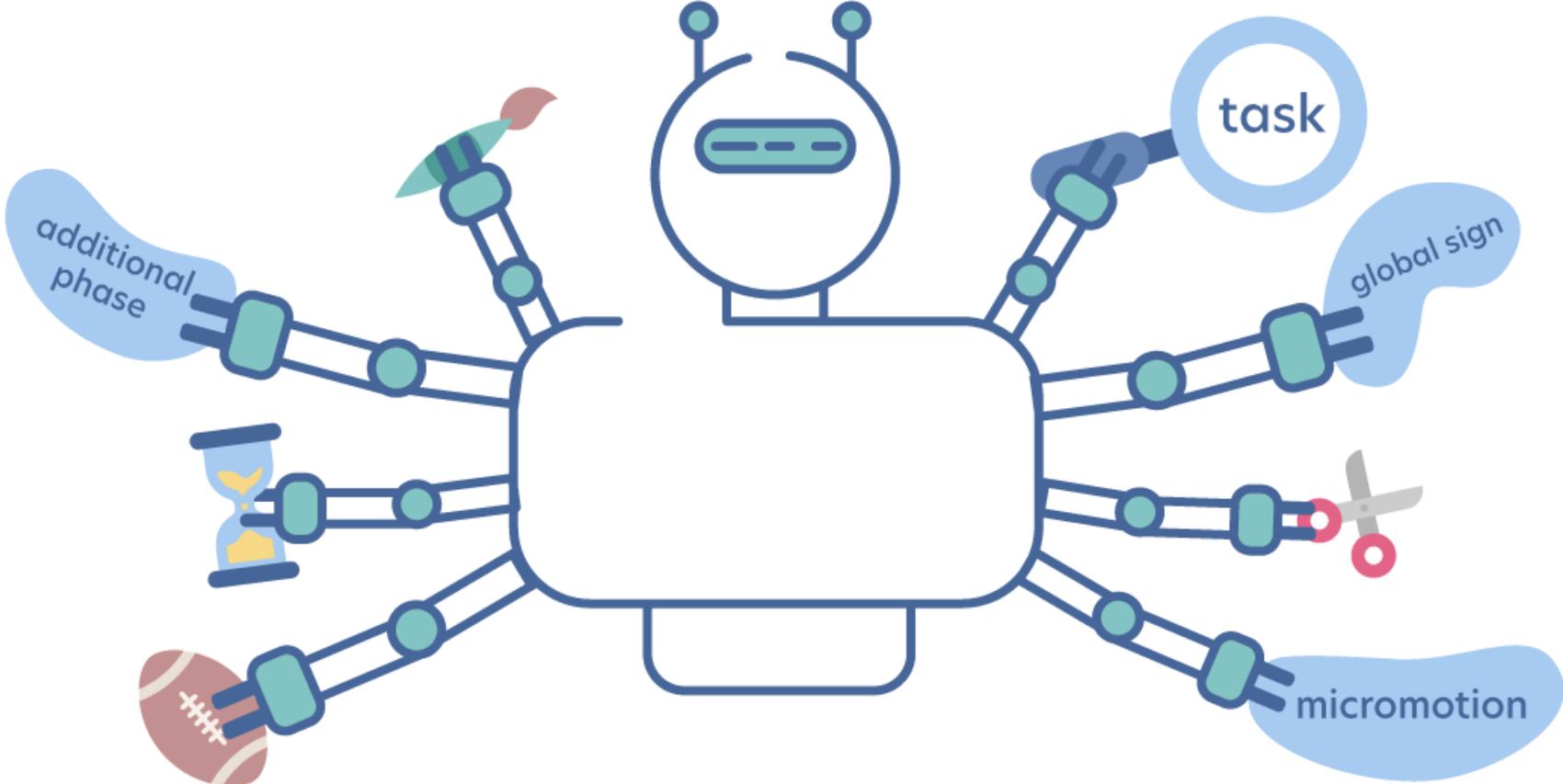


Conclusions





More likely to learn physical features
than spurious correlations?





UNIVERSITY
OF WARSAW

ICFO^R

The Institute of Photonic
Sciences



Universität
Hamburg



M. Tomza



P. Huembeli



K. Kottmann



N. Käming



A. Dauphin



M. Lewenstein



K. Sengstock



C. Weitenberg



/Shmoo137

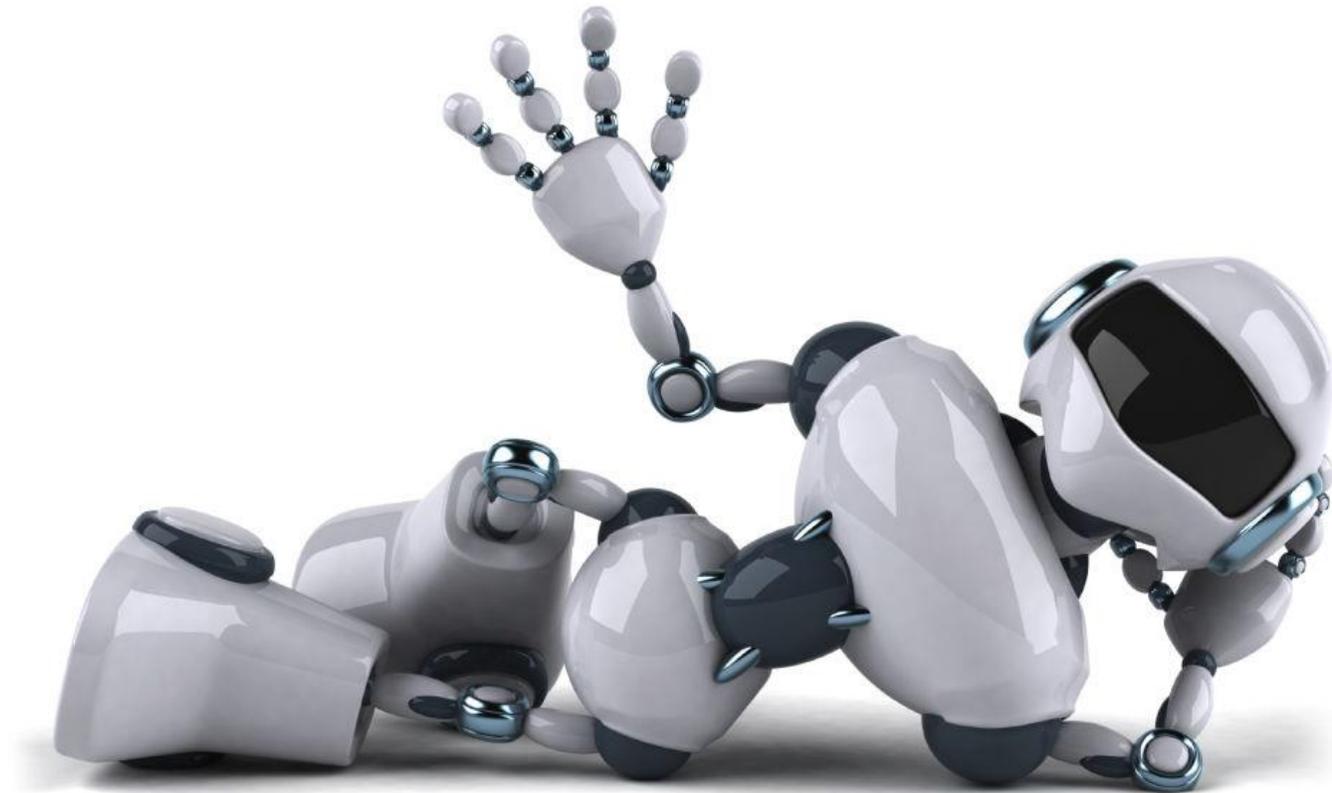
If you want to know more...

A. Dawid et al (2022)
Mach. Learn.: Sci. Technol. **3** 015002 (2022)

N. Käming, A. Dawid et al (2021)
Mach. Learn.: Sci. Technol. **2** 035037

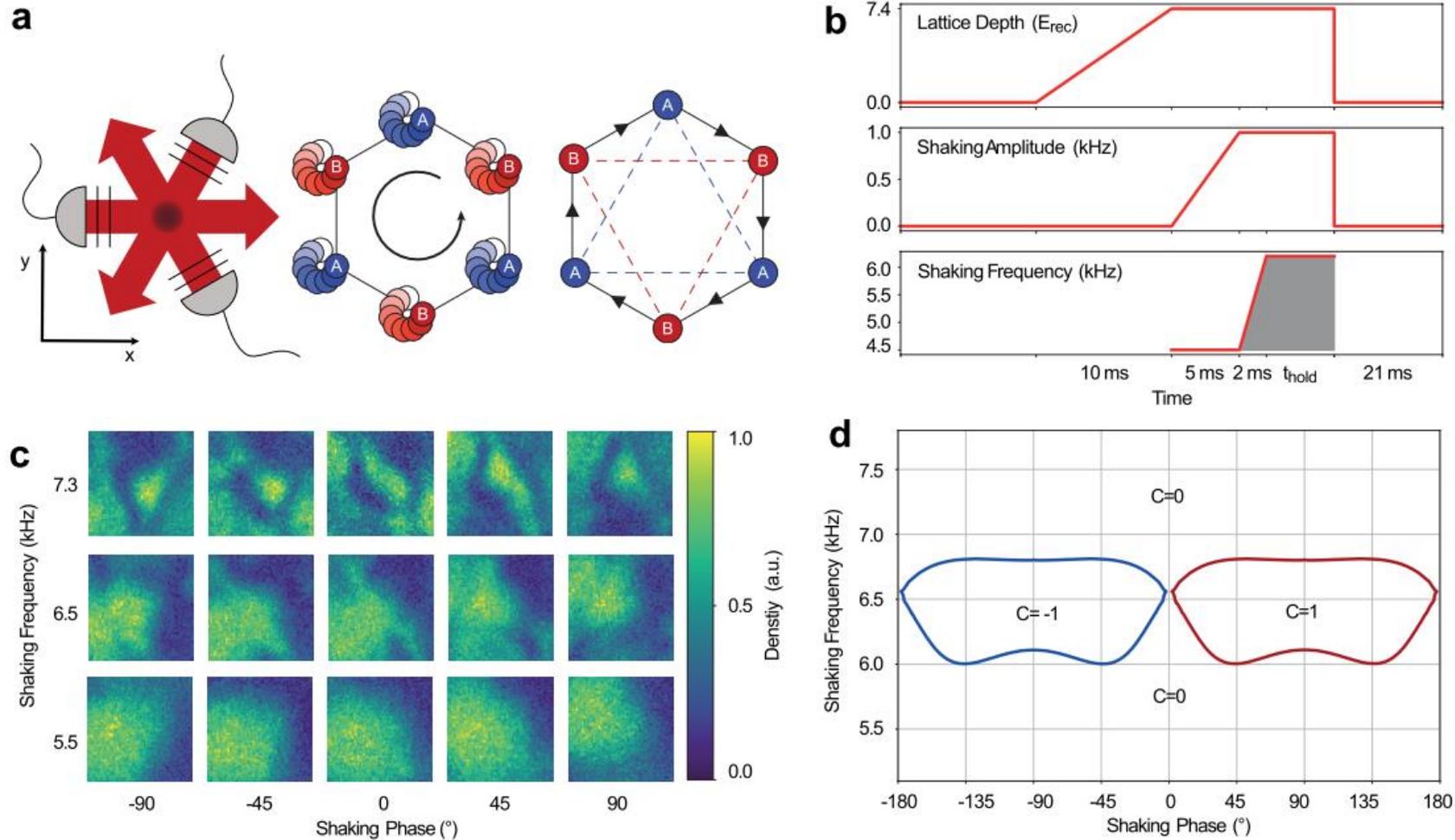
A. Dawid et al (2020)
New J. Phys. **22** 115001

Thank you for your attention!



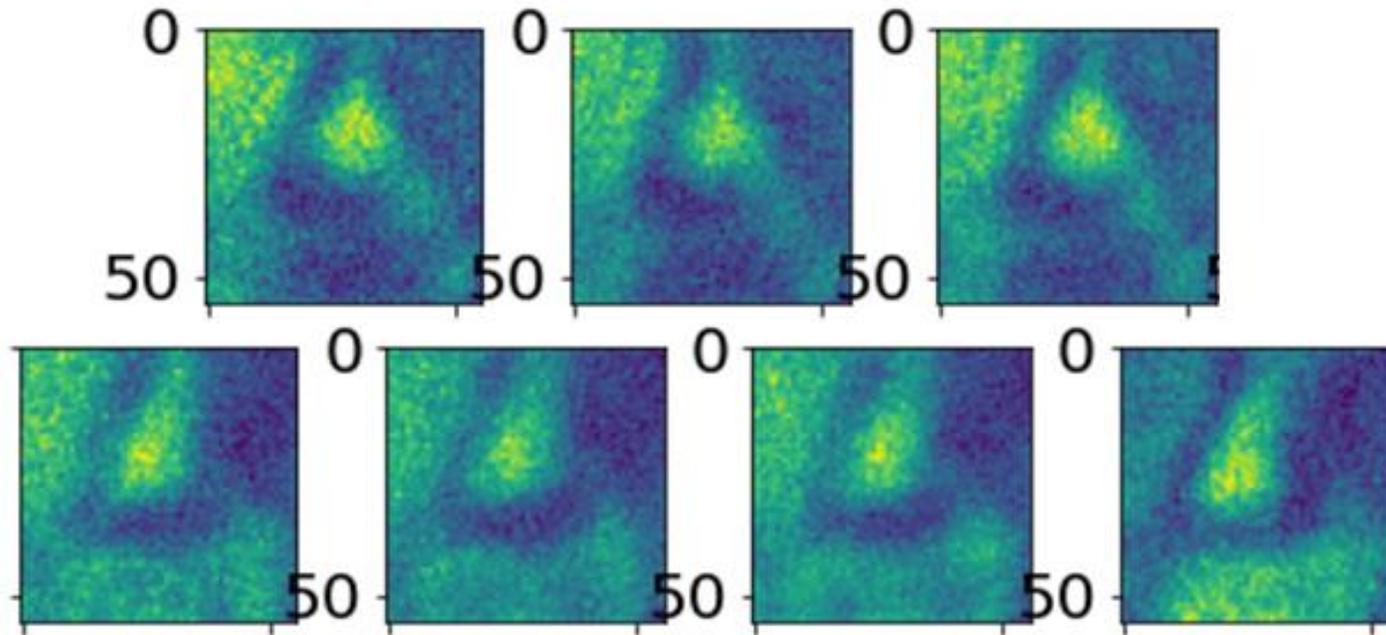
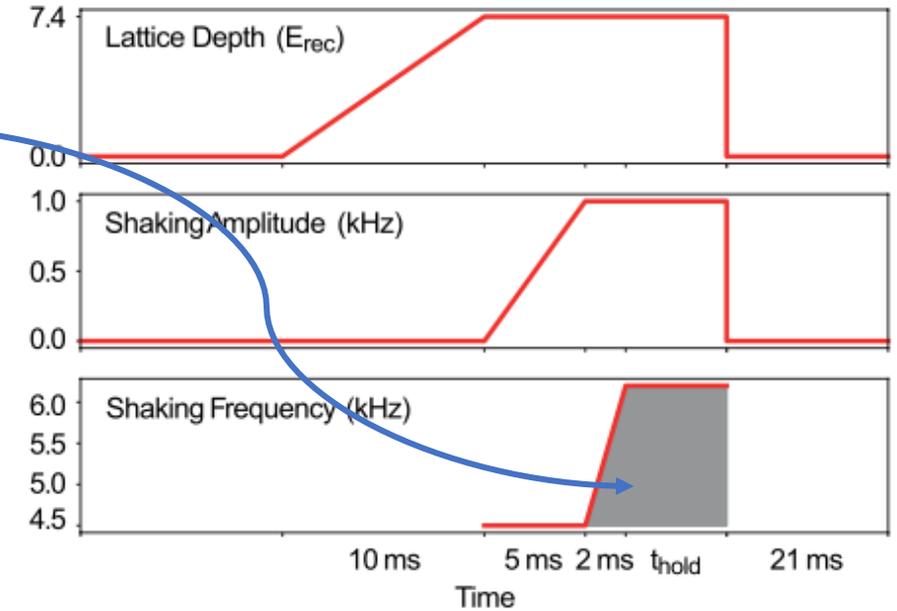
Topological Haldane model

realized via Floquet-driving of ultracold fermions (^{40}K) in a honeycomb lattice



Micromotion phase

shaking frequency = 7.4 Hz
shaking phase = 90°
different micromotion phases



RUE vs LEES

